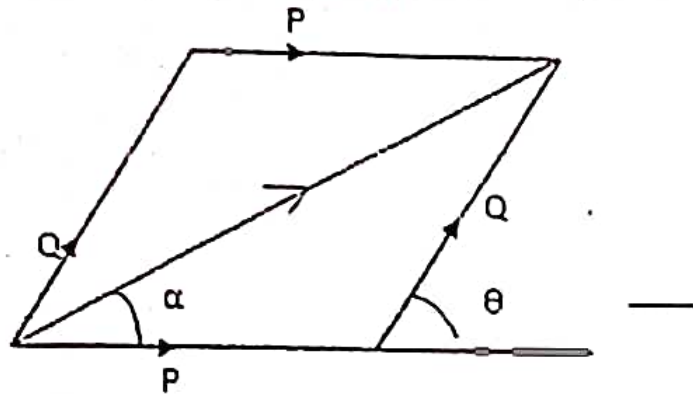


LIST OF FOEMULAE

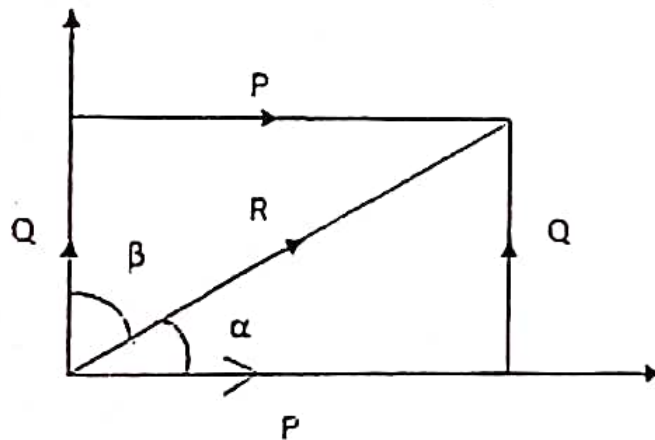
- Resultant of force acting in a straight line:
 - a) same direction: $R = P + Q$
 - b) Opposite direction : $R = P - Q$
- Resultant of two concurrent forces:

$$R = \sqrt{P^2 + Q^2 + 2PQ \cos \theta}$$

$$\alpha = \tan^{-1} \frac{Q \sin \theta}{P + Q \cos \theta}$$



- Components of given force in two given directions:



- Resultant of number of co-planar concurrent forces:

$$R \cos \theta = \sum p_i \cos \theta_i = \sum H = X$$

$$R \sin \theta = \sum p_i \sin \theta_i = \sum V = Y$$

$$R = \sqrt{X^2 + Y^2}$$

$$\theta = \tan^{-1} \frac{Y}{X}$$

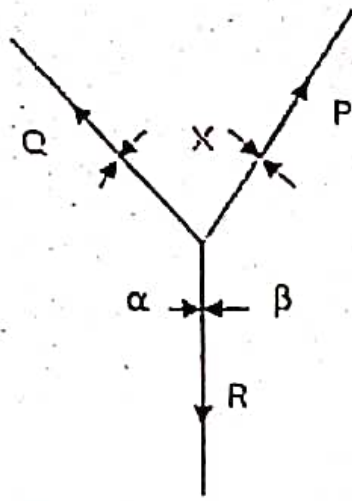
- Resultant of co-planar forces:

$$R = \sum P_i$$

$$\bar{x} = \frac{\sum P_i X_i}{\sum P_i}$$

Where X_i are distance of various forces from a reference axis \bar{x} is the distance (perpendicular) of R from reference axis.

- Mechanical advantage of a lever = $\frac{\text{Power arm}}{\text{Load arm}}$
- Lami's theorem:



$$\frac{P}{\sin \alpha} = \frac{Q}{\sin \beta} = \frac{R}{\sin \chi}$$

- Friction force: $F = \mu N$; $N = \text{normal reaction}$
- Total reaction; $R = \sqrt{F^2 + N^2}$
($F' = F_{\max}$)

Angle of friction; $\theta = \tan^{-1} \frac{F}{N}$

Also, $\mu = \tan \theta$

- Angle of response : $\alpha = \phi$
- Work done by a varying force:

$$W = \int_0^s F \cdot \delta S$$

$S = \text{Total distance covered}$

- If a body freely falls from a height H , then velocity on reach the ground;

$$v = \sqrt{2gH}$$

- If a body is projected vertically with initial velocity u , then the maximum height attained by it is:

$$H = \frac{U^2}{2g}$$

- Distance covered in the n th second

$$D_n = u + \frac{a}{2}(2n - 1)$$

- Motion of a particle in a plane

$$u = \frac{dx}{dt}; v = \frac{dy}{dt}$$

$$v = \sqrt{u^2 + v^2}$$

$$\alpha_x = \frac{du}{dt} = \frac{d^2x}{dt^2}; \alpha_y = \frac{dv}{dt} = \frac{d^2y}{dt^2}$$

- Work done by a force field $F(x,y,z)$ along path 1-2 is given by:

$$W_{1-2} = \int_1^2 F dr = V_1(x,y,z) - V_2(x,y,z)$$

Where, $V(x,y,z)$ is the potential energy function (scalar function).

- For a conservative force field:

$$\int F \cdot dr = 0, \text{ and}$$

$$F = -\Delta V$$

- Equation of trajectory

$$Y = x \tan \alpha - \frac{1}{2g} \frac{x^2}{u^2 \cos^2 \alpha}$$

(a) Motion of projectile up an inclined plane:

$$\text{Time of flight, } T = \frac{2u \sin(\alpha - \beta)}{g \cos \beta}$$

[β : inclination of plane]

Range up of the plane:

$$R = \frac{2u \cos \alpha \sin(\alpha - \beta)}{g \cos^2 \beta}$$

$$R_{\max} = \frac{u^2}{g(1 + \sin \beta)} \text{ at } \alpha = \frac{\pi}{4} + \frac{\beta}{2}$$

c) motion of a projectile projected horizontally at a height above the ground:

$$x = ut$$

$$y = \frac{1}{2} gt^2$$

$$\frac{x^2}{y} = \frac{2u^2}{g} = \text{constant}$$

- Elastic collision: both momentum and (kinetic energy) are conserved

$$m_1 u_1 + m_2 u_2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2$$

$$\frac{1}{2} m_1 u_1^2 + \frac{1}{2} m_2 u_2^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2$$

- Inelastic collision: only momentum is conserved

$$m_1 u_1 + m_2 u_2 = m_1 v_1 + m_2 v_2$$

- Coefficient of electricity or restitution:

$$e = \frac{v_2 - v_1}{u_2 - u_1}$$

$e = 1$ for perfectly elastic bodies, $e = 0$ for plastic impact

- Apparent weight in a lift:

Upward moving lift:

$$w_{\text{app}} = mg \left(1 + \frac{a}{g} \right) n$$

Downward moving Lift:

$$w_{\text{app}} = mg \left(1 - \frac{a}{g} \right) n$$

- Total kinetic energy of a body:

$$TE = \frac{1}{2} mv^2 + \frac{1}{2} I\omega^2$$

- Momentum of inertia of a thin circular ring:

(a) About an axis perpendicular to plane of ring:

$$I = \frac{1}{2} MR^2$$

(b) About any diameter:

$$I = \frac{1}{2} MR^2$$

(b) About a tangent in the plane of ring:

$$I = \frac{3}{2} MR^2$$

(d) About a tangent perpendicular to the plane of ring:

$$I = \frac{1}{2} MR^2$$

- Momentum of inertia of a uniform circular disc:

$$I = \frac{1}{2} MR^2$$

(About an axis perpendicular to plane of disc:)

- Momentum of inertia of a thin uniform rod;

(a) About an axis passing through the centre of length and perpendicular to the length:

$$I = \frac{1}{2} Ml^2$$

(b) About its axis:

$$I = \frac{1}{2} MR^2$$

(C) Hollow rod:

$$I = MR^2$$

- Moment of inertia of hollow sphere:

$$I = \frac{2}{3} MR^2$$

- Moment of inertia of solid sphere

$$I = \frac{2}{5} MR^2$$

- Motion of a cylinder rolling without slipping on an inclined plane;

$$\alpha = \frac{mg, \sin \theta}{m + \frac{1}{r^2}} = \frac{2}{3} g, \sin \theta [\alpha < g]$$

$$F = \frac{1}{3} mg, \sin \theta; F < mg$$

$$\mu = \frac{1}{3} \tan \theta$$