

Reg. No. :

Name :

**VI Semester B.Tech. Degree (Reg./Sup./Imp. – Including Part Time)
Examination, May 2013
(2007 Admn. Onwards)
PT 2K6/2K6 EC/AEI 602 : CONTROL SYSTEMS**

Time : 3 Hours

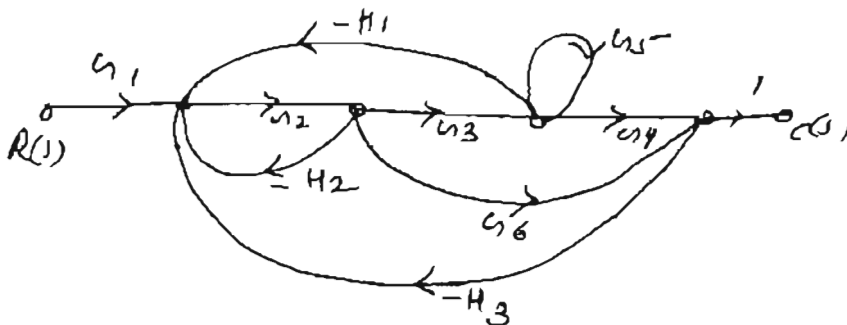
Max. Marks : 100

Instruction : Answer all questions.

- I. a) Explain the concept of feedback. What are the advantages of closed loop system over open loop system ?
- b) Define pole, zeros, order and type of a system.
- c) Explain Nyquist stability criterion.
- d) Draw the circuit of a lag network. Sketch its Bode plots.
- e) State any five properties of Z transforms.
- f) What is bilinear transformation ? How it is useful for stability analysis of discrete system ?
- g) Define state, state variables and state space.
- h) Derive the relation between transfer function and state model of a discrete system. (8×5=40)

- II. a) Find the transfer function of the system whose signal flow graph is shown below

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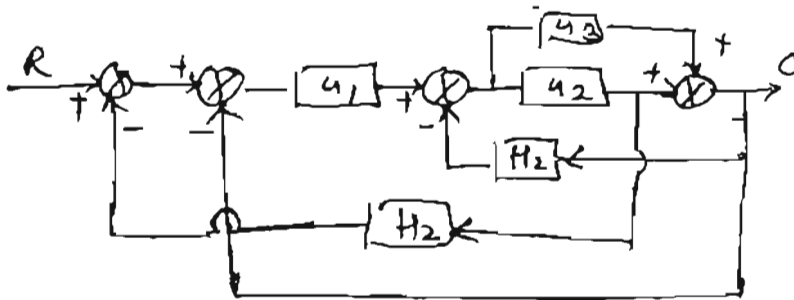


OR



b) Find C/R of the following system.

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III. a) Find the values of K and K_n for the system shown below such that the peak overshoot for unit step input is 0.2 and peak time is 1 sec. With these values find rise time and settling time.

12

b) Define phase margin and gain margin.

3

OR

c) Sketch the polar plot and find gain margin and phase margin for the system

with open loop transfer function $\frac{1}{S(1+S)(1+2S)}$.

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IV. a) Find the Z transforms of

i) $t e^{-t}$ and

ii) $\sin \omega t$.

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b) Explain cyclic and multirate sampling.

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OR

c) Solve the difference equation :

$$c(k+2) + 3c(k+1) + 2c(k) = u(k);$$

$$c(0) = 1, c(1) = -3; c(k) = 0, k < 0.$$

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d) Explain Jury's stability test.

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V. a) A discrete system is given by

$$y(k + 2) + 5y(k + 1) + 6y(k) = u(k)$$

$$y(0) = y(1) = 0, T = 1 \text{ sec.}$$

Find :

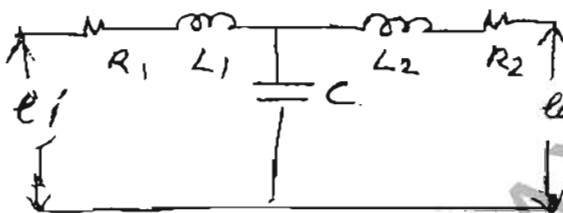
- i) A state model in Canonical form
- ii) State transition matrix
- iii) For $u(k) = 1, k \geq 1$, find $y(k)$.

15

OR

b) Obtain a state model for the network given below :

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c) What is state transition matrix ? Explain its properties.

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GEC VIJAYANAD