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Name:....

VI Semester B.Tech. Degree (Regular/Supplementary/Improvement – Including Part Time) Examination, May 2014 (2007 Admn. Onwards)

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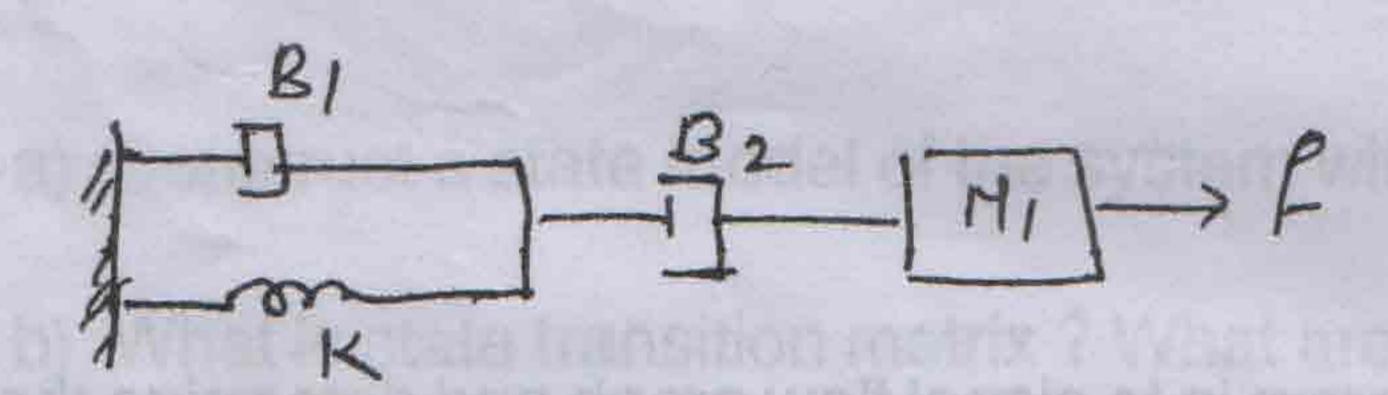
PT2K6/2K6 EE 606 (C): LINEAR SYSTEM ANALYSIS

Time: 3 Hours

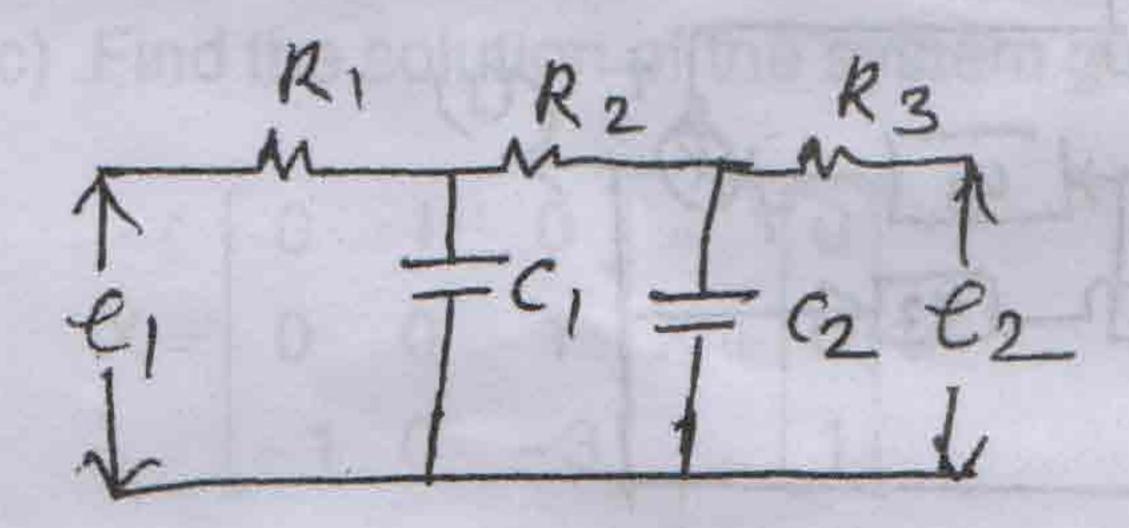
Max. Marks: 100

Instruction: Answer all questions.

- 1. a) Differentiate between static and dynamic systems.
 - b) Obtain the differential equations describing the following system:



c) Obtain the transfer function of the following network:



- d) State and explain Mason's gain formula.
- e) Sketch and mark the specifications the unit step response of an under damped second order system.

c) Find the Fourier transform of y (t) = e⁻²¹ f(t) where f(t) has the Fourier

- f) Explain the concept of stability.
- g) Compare state space and transfer function approaches.
- h) What is meant by controllability? Explain.

 $(8 \times 5 = 40)$



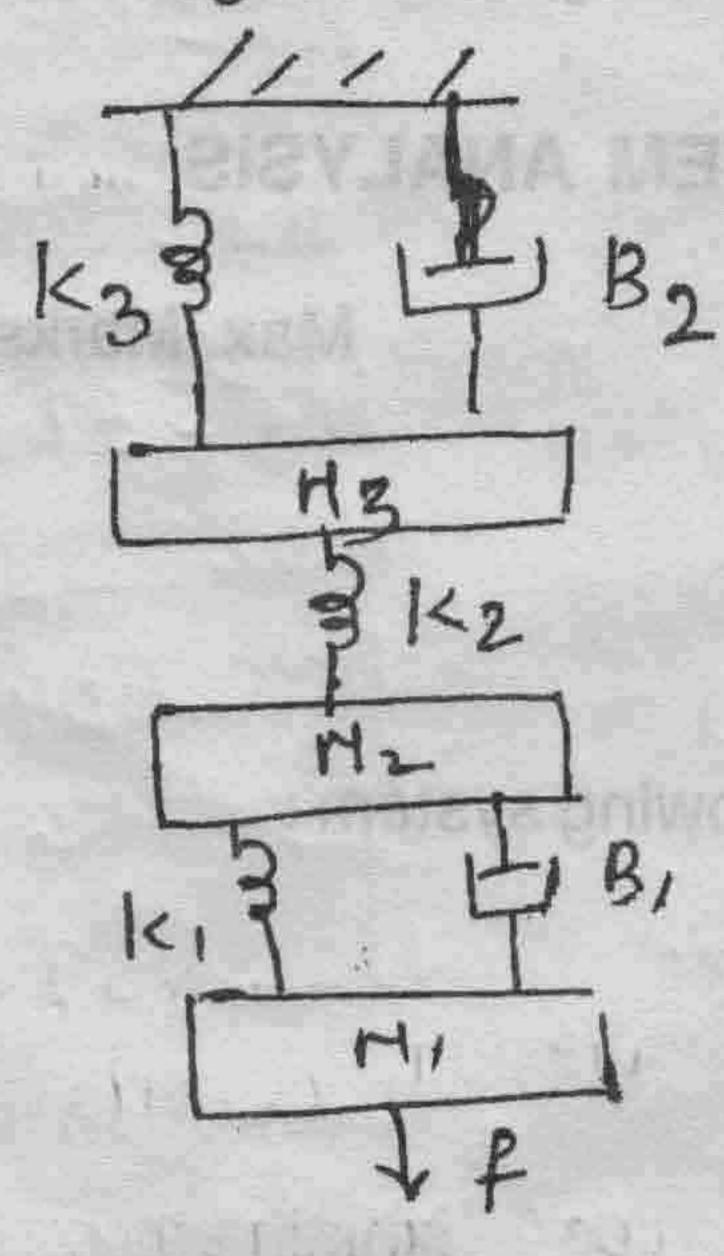
2. a) With suitable examples explain the modelling of pneumatic and thermal systems.

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OR

b) For the system shown below find the Force-Voltage and Force-Current analogous circuits.

15



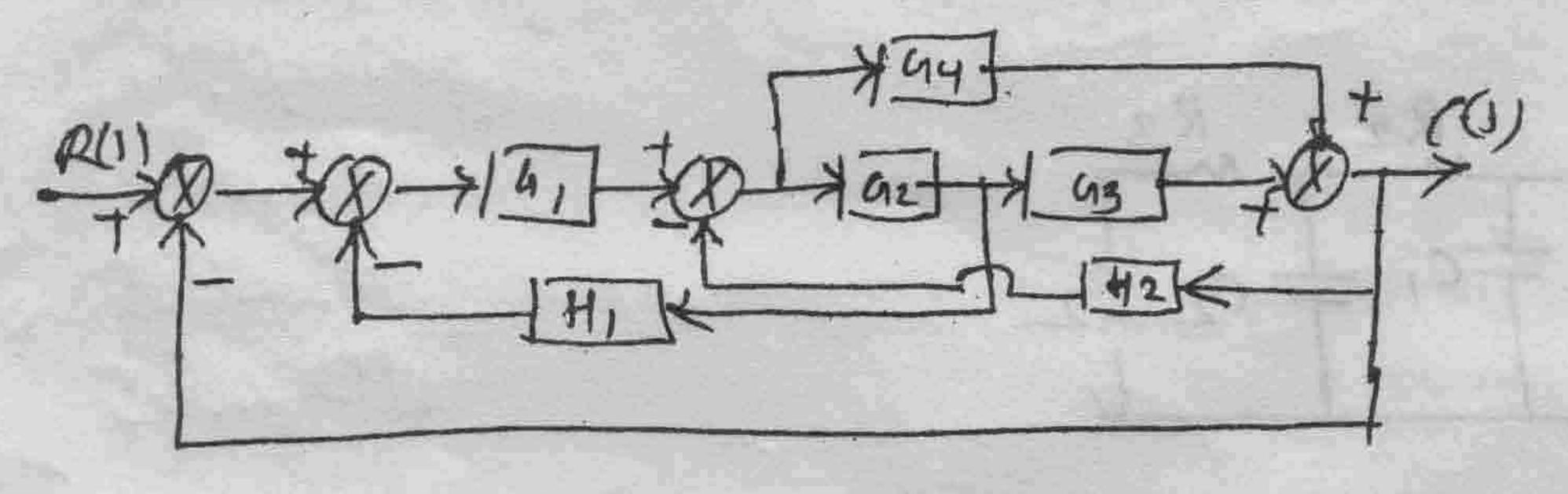
3. a) Convert the following block diagram in to signal flow graph and determine the transfer function:

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What is meant by controllability? Explain.

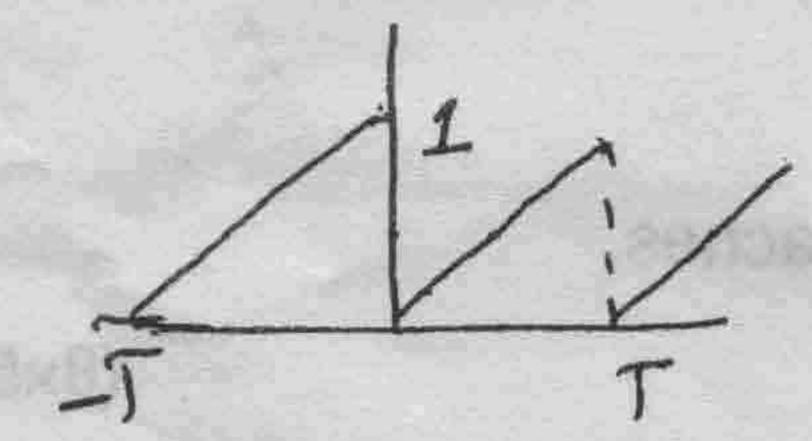
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OR

b) Find the Fourier series of the function shown below:

2



c) Find the Fourier transform of y (t) = e^{-2t} f(t) where f(t) has the Fourier

transform
$$F(w) = \frac{10}{jw + 4}$$
.

7

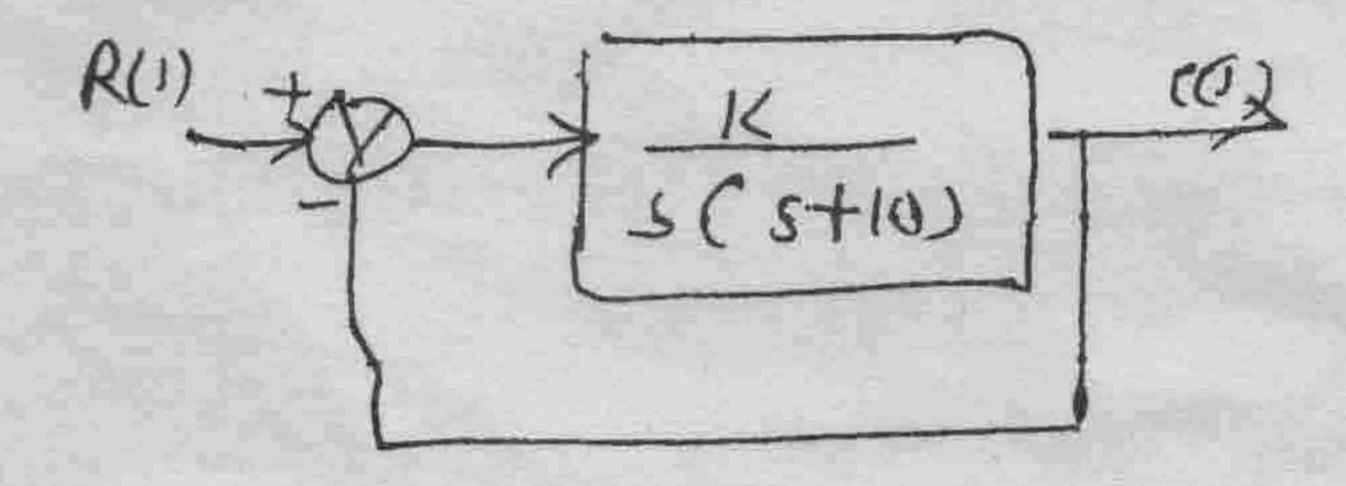


4. a) Test the stability of the system whose characteristic equation is $s^6 + s^5 + 3s^4 + 3s^3 + 3s^2 + 2s + 1 = 0$

b) Define steady state error and steady state error coefficients.

10

c) For the system shown below find the value of K so that the damping ratio is 0.5. For this value of K find peak time and peak over shoot. Derive the relations used:



5. a) Construct a state model of the system with transfer function $\frac{10(s+4)}{s(s+1)(s+3)}$. 7

b) What is state transition matrix? What are its properties? Explain any one method to find it.

OR c) Find the solution of the system given by:

$$\dot{X} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & 0 & -3 \end{bmatrix} X + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

$$X(0) = [1 \ 0 \ 0]^{T}$$