



Reg. No. :

Name :

8/5 Sem EC
M 26861
Apr' 2015

VIII Semester B.Tech. Degree (Reg./Sup. – Including Part Time)

Examination, April 2015

(2007 Admn. Onwards)

PT2K6/2K6 EC 801 : RADAR AND NAVIGATION

Time : 3 Hours

Max. Marks : 100

PART – A

Answer all questions.

- I. a) Write the different radar frequencies used for transmission.
b) Explain, how PRF affects range ambiguity.
c) What is digital MTI processing ? Also write the advantages.
d) Write the limitations to MTI performance.
e) Explain the working of a crossed field Amplifier.
f) Discuss about reflector antenna.
g) What is track stabilized antenna ? Explain.
h) Briefly explain about LF/MF four course radio range.

(8×5=40)

PART – B

- II. a) i) Derive the radar range equation. 10
ii) Discuss the factors affecting the maximum range. 5
- OR
- b) Write the different losses associated with the radar system. 15
- III. a) i) Explain about AMTI radar. 5
ii) What is the principle used in Monopulse radar ? With a block diagram explain the working of monopulse tracking radar. 10

OR

P.T.O.



- b) i) Write about automatic tracking with surveillance Radar. 5
ii) With a block diagram, explain the conical scan method of tracking. Also write the characteristics. 10
- IV. a) Using Waveforms explain the different Radar displays. 15
- OR
- b) i) With a block diagram, explain a superheterodyne receiver. 9
ii) Explain the radiation pattern in phased array antennas. 6
- V. a) i) Explain about Decca receiver with block diagram. 10
ii) Write a note on doppler navigation. 5
- OR
- b) With block diagrams explain the working of coherent and incoherent pulsed doppler system. 15
-