Name	Utech
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Invigilator's Signature :	

#### CS/B.TECH(IT)/SEP.SUPPLE/SEM-7/IT-703A/2012

# 2012

## **COMPUTER GRAPHICS**

Time Allotted : 3 Hours

Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words

as far as practicable.

# GROUP – A ( Multiple Choice Type Questions )

1. Choose the correct alternatives for any *ten* of the following :

 $10 \times 1 = 10$ 

- i) The slope of the cubic Bezier curve at the start of the curve in controlled by
  - a) first control point
  - b) first two control points
  - c) first three control points
  - d) all four control points.
- ii) A projection in which all three foreshortening factors are kept equal is called
  - a) Isometric projection b) Diametric projection
  - c) Trimetric projection d) none of these.
- iii) If (x, y, 0) is a point in the homogeneous coordinate system then it represents
  - a) origin in 2D coordinate system
  - b) origin in 3D coordinate system
  - c) a point at infinity
  - d) point (x, y) in 2D coordinate system.

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CS/B.TECH(IT)/SEP.SUPPLE/SEM-7/IT-703A/2012 In Bresenham's Circle generation algorithm, if (x, y) is iv) the current pixel position, then the y value of the next pixel position is y or y + 1y alone a) b) y + 1 or y - 1y or y - 1.c) d) In Cohen-Sutherland line clipping algorithm, if the v) codes of the two points P & Q are 0101 & 0001 then the line segment joining the points P & Q will be ..... the clipping window. totally outside partially outside a) b) c) totally inside d) none of these. ..... acts as anode in CRT. vi) The phosphorous coating a) The glass panel b) c) The deflector None of these. d) In the inside-outside test of polygon, if the winding vii) number of a point is zero then the point lies ..... the polygon. inside a) b) outside d) c) on as vertex of. viii) Sutherland-Hodgman algorithm is used for line clipping b) point clipping a) polygon clipping hybrid clipping. d) c) the blending functions of Bezier curves are ix) a) **Splines** Bernstein polynomials b) Lagrangian polynomials c) d) Newton polynomials. *Z*-buffer algorithm is used for X) frame buffer removal a) visible surface detection b) rendering c) animation. d)

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- xi) Refresh rate is
  - the rate at which the number of bit planes are a) accessed at a given time
  - the rate at which the picture is redrawn b)
  - the frequency at which the aliasing takes place c)
  - the frequency at which the contents of the frame d) buffer is sent to the display monitor.
- The Look up table technique ..... the number of xii) intensity levels.
  - decreases a)
- b) increases
- c) removes
- d) gives no effect on.

#### **GROUP – B**

## (Short Answer Type Questions)

Answer any *three* of the following.  $3 \times 5 = 15$ 

- 2. Using Bresenham's line drawing algorithm, determine successive pixel positions along the line path with end points (20, 10) and (30, 18).
- Describe Bresenham's line generating algorithm. 3.
- Use the Cohen-Sutherland line clipping algorithm to clip two 4. lines with points  $p_1(40,15), p_2(75,45)$ end and  $p_3(70,20), p_4(100,10)$  respectively; against a rectangular window with vertices A (50, 10), B (80, 10), C (80, 40) and D (50,40).
- 5. Perform a  $45^{\circ}$  rotation of triangle A (0,0), B (5, 2) and *C*(3,7).
  - a) about the origin and
  - about P(-1, -1). b)
- 6. Derive general parallel projection transformation matrix.

#### **GROUP - C**

## (Long Answer Type Questions)

Answer any *three* of the following.  $3 \times 15 = 45$ 

- 7. Why do we prefer incremental line drawing algorithm a) over DDA line drawing algorithm ?
  - What is homogeneous coordinate Why is b) ? а homogeneous coordinate system needed in transformation matrix ?

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- c) How much memory is needed for the frame buffer to store a 640 × 400 display having 16 gray levels ?
- d) Describe Mid-point circle drawing algorithm.

2 + 3 + 4 + 6

- 8. a) Derive the transformation matrix that rotates an object point  $\theta^{\circ}$  about the origin.
  - b) Explain the reflection of a 2D figure on y = mx + c. Derive its transformation matrix.
  - c) Magnify the triangle with vertices A(0,0), B(1, 1) and C(5, 2) to twice its size while keeping C(5, 2) fixed.

5 + 5 + 5

- 9. a) Explain the term 'control points' in the context of curve generation.
  - b) Find equation of Bezier curve which passes through points (0,0) and (-2, 1) and is controlled through points (7,5) and (2,0).
  - c) Derive and plot Beizer blending functions for cubic curves (n = 3). 3 + 7 + 5
- 10. a) Describe Depth-Buffer method of visible surface detection.
  - b) The pyramid defined by the coordinates A (0, 0, 0), B (1, 0, 0), C (0, 1, 0) and D (0, 0, 1) is rotated 45° about line L that has the direction V = J + K and passing through point C (0, 1, 0). Find the coordinate of the rotated figure.

5 + 10

- 11. Write short notes on any *three* of the following :  $3 \times 5 = 15$ 
  - a) Window to view port coordinates transformation
    - b) Gourad Shading
    - c) Phong's Shading model
    - d) CMY colour model
    - e) Boundary fill algorithm
    - f) Painter's algorithm
    - g) Virtual reality.

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