	Utech
Name:	
Roll No.:	
Invigilator's Signature :	

# CS/B.Tech(ECE)/SEM-8/EC-804D/2012 2012

# **REMOTE SENSING**

Time Allotted: 3 Hours Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

# GROUP - A ( Multiple Choice Type Questions )

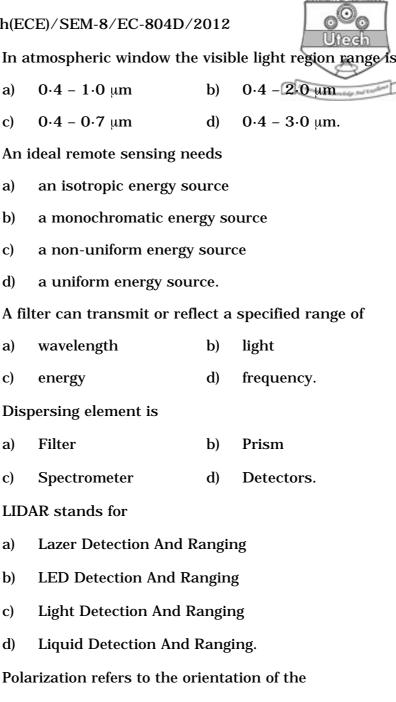
- 1. Choose the correct alternatives for any *ten* of the following :  $10 \times 1 = 10$ 
  - i) The relationship between the wavelength (  $\lambda$  ), frequency (  $\nu$  ) and velocity of light ( c ) of EMR is based on the formula
    - a)  $c = \lambda v$
- b)  $c = \lambda/\nu$
- c)  $\lambda = cv$

- d)  $\lambda = c/\nu$ .
- ii) The amount of energy characterizing a photon is determined using Plank's general equation
  - a) Q = h/v
- b) Q = hv
- c) h = Qv
- d) v = Qh.

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[ Turn over

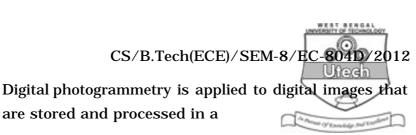
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- iii)
  - a)  $0.4 - 1.0 \, \mu m$
- b)
- $0.4 0.7 \mu m$ c)
- d)
- An ideal remote sensing needs iv)
  - a) an isotropic energy source
  - a monochromatic energy source b)
  - c) a non-uniform energy source
  - d) a uniform energy source.
- A filter can transmit or reflect a specified range of v)
  - wavelength a)
- b)

c) energy

- d)
- Dispersing element is vi)
  - Filter a)
  - c) Spectrometer
- d)
- LIDAR stands for vii)
  - a) **Lazer Detection And Ranging**
  - **LED Detection And Ranging** b)
  - **Light Detection And Ranging** c)
  - Liquid Detection And Ranging. d)
- viii) Polarization refers to the orientation of the
  - E-H fields a)
- b) H-field
- c) Transverse E-field
- d) E-field.



- a) Computer
- b) Processor
- c) Memory

ix)

- d) None of these.
- x) For representing 3D earth's surface we use
  - a) Photogrammetry
  - b) DTM or DEM generation
  - c) Orthorectification
  - d) Y-parallax.
- xi) Radargrammetry is a method that derives a topographic map from two overlapping
  - a) LIDAR images
- b) SONAR images
- c) Rarad images
- d) Digital images.
- xii) Digital image processing is carried out using
  - a) Mainframe-based
- b) Microcomputer-based
- c) Minicomputer-based
- d) All of these.

#### **GROUP - B**

### (Short Answer Type Questions)

Answer any three of the following.

 $3 \times 5 = 15$ 

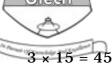
- 2. What is remote sensing? Explain about distance remote sensing. 2+3
- 3. Distinguish between active and passive remote sensing.
- 4. What do you understand by digital image?
- 5. What is radargrammetry?
- 6. Write about the advantages of GIS over DBMS.

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# (Long Answer Type Questions)

Answer any three of the following.



- 7. a) What are Thematic maps?
  - b) Write about the role of Digital Image Processing technology in Remote Sensing.
  - c) What is a Multi Spectral Remote Sensing System?

5 + 5 + 5

8. What do you understand by digital image? What is sensor? Explain about different sensors used in remote sensing.

8 + 7

- 9. What is photogrammetry? Explain the photogrammetric process with a suitable workflow diagram. What is the difference between LIDAR and photogrammetry? 2 + 9 + 4
- 10. Define GIS. Describe the key components of GIS. Describe GIS in the context of information infrastructure. 2 + 7 + 6
- 11. Write short notes on any *three* of the following :  $3 \times 5$ 
  - a) Role of Shadow to measuring height
  - b) Limitations of GIS
  - c) Management of project
  - d) 4D GIS
  - e) GPS
  - f) Microwave remote sensing system.

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