

1. Preparatory Function [G-Code]

It determines how the tool is to move to the programmed target.

i.e. Linear, Circular, PTP @ any specific operation [Rough turning, Facing, finishing etc]

Ex:- G100	Rapid traverse of tool.
G101	Linear — — —
G102	Circular interpolation in C.W
G103	— — in C.C.W.
G104	Dwell [tool resides for sometimes to get flat surface at the bottom position of drilling]
G171	Rough turning
G170	- Finishing
G172	- Facing
G183	- Peck drilling.

2. Miscellaneous Code [M-Code]

It is used to control the Machine operation other than for co-ordinate Movement.

i.e. M106	Tool change
M00	- Program stop.
M01	- optional stop
M30	- End of program.
M98	- Sub program call.

NC Program :-

It is a manual program in which set of instructions are coded by number, letter, symbols which are executed by a sequential manner through a simulation software

Namely : See NC Mill 6.0v for Milling operation
See NC turn 6.0v for turning operation

3 Basic Motion [NC]

1. Linear Motion / Continuous Motion:

The cutting tool travels in a linear manner. Ex G100
G101

2. Contour Motion:

The tool will travel in a circular path. Ex: G102 C.W
G103 CCW

3. Point to Point [PTP]: - Cutting tool will move from one point to another point to perform the activity specified
Ex: - G183 [peck drilling]

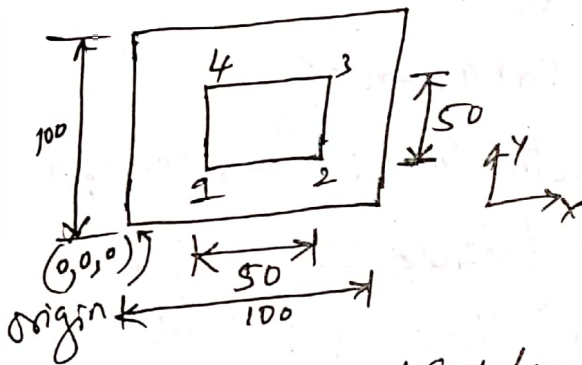
CNC Program:-

Here the CAD model is prepared and the programmer will define the tool path so that the computer itself generate the program through software

Software:- CapS mill
CapS turn.

2 Methods of Programming:-

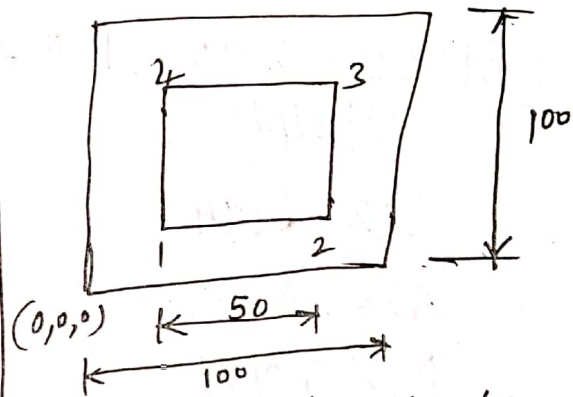
Absolute programming [G190]



Here coordinates value are defined from the fixed origin

- | x | y |
|------------|---|
| 1 (25, 25) | |
| 2 (75, 25) | |
| 3 (75, 75) | |
| 4 (25, 75) | |

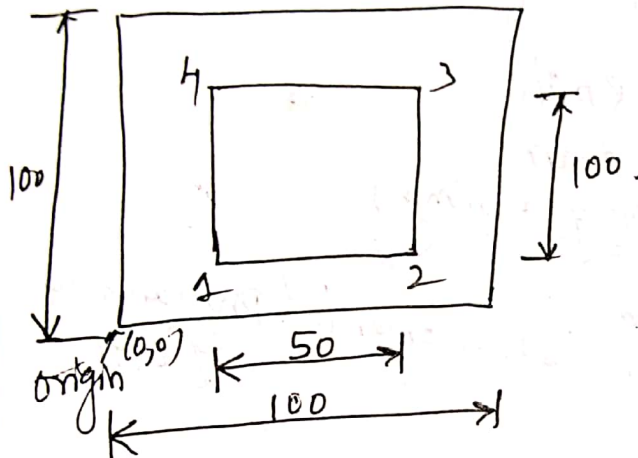
Incremental programming [G191]



Here the coordinates value are defined by taking previous value as origin.

- | x | y |
|------------|---|
| 1 (25, 25) | |
| 2 (50, 0) | |
| 3 (0, 50) | |
| 4 (-50, 0) | |
| 1 (0, -50) | |

1. Write a Manual Part programming to perform linear operation for the given profile. Take cutter diameter 10mm & depth of slot 2mm.



1 (25, 25)
 2 (75, 25)
 3 (75, 75)
 4 (25, 75)

[BILLET X100 Y100 Z10.

O1244

G121 G194

G128 X0 Y0 Z0

M06 T0101

M03 S1000

Program no

metric (mm); feed (mm/min)

Reference position of tool.

tool change; tool no

Spindle C.W; rpm (Speed)

G100 X25 Y25 Z5

G101 Z-2 F40 (1)

G101 X75 Y25 (2)

X75 Y75 (3)

X25 Y75 (4)

X25 Y25 (1)

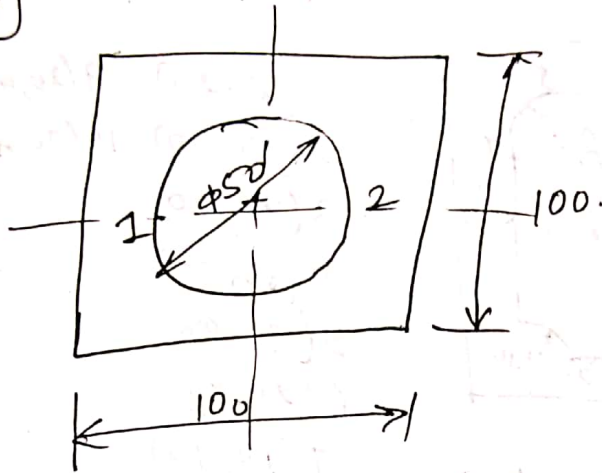
G100 Z5

G128 X0 Y0 Z0

M05

M30]

2. Write a Manual part program to perform circular operation for the given profile. Take: BILLET 100x100x10



[BILLET X100 Y100 Z10.

O1445

G21 G94

G28 X0 Y0 Z0

M06 T0101

M03 S1000

G700 X25 Y50 Z5

G701 Z-2 F40

G702 X75 Y50 R25

G702 X25 Y50 R25

G700 Z5

G728 X0 Y0 Z0

M05

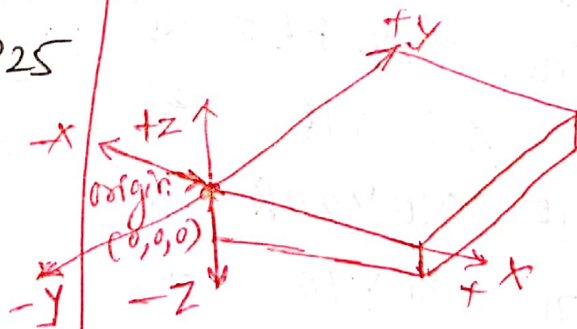
M30]

1 (25, 50)

2 (75, 50)

1 (25, 50)

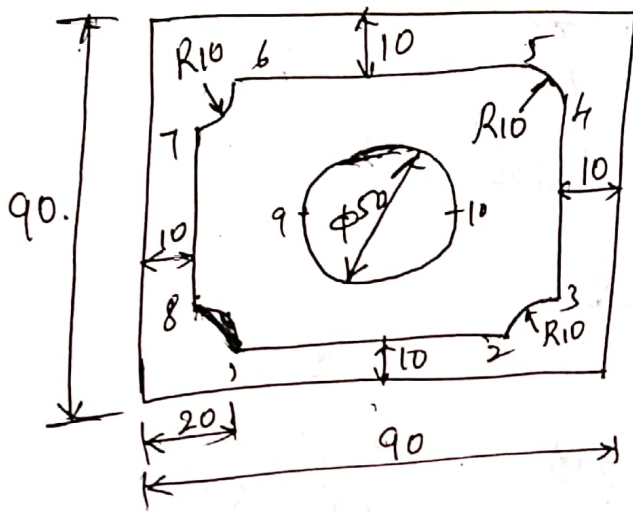
Coordination System for Milling operation



X, Y are dimension of w/p along X and Y direction

Z represent depth / thickness of w/p.

3. Write a manual part program to perform profile cutting operation for the given profile take cutter dia 10mm



- 1 (10, 20)
- 2 (20, 80)
- 3 (80, 80)
- 4 (80, 70)
- 5 (70, 80)
- 6 (20, 80)
- 7 (10, 70)
- 8 (10, 20)
- 9 (20, 45)
- 10 (70, 45)

[BILLET X 90 Y 90 Z 20.

O1475

G121 G194

G128 X0 Y0 Z0.

M06 T0101

M03 S1500

G100 X20 Y10 Z5

G101 Z-2 F40 (1)

X70 Y10 (2)

G102 X80 Y20 R10 (3)

G101 X80 Y70 (4)

G103 X70 Y80 R10 (5)

G101 X20 Y80 (6)

G102 X10 Y70 R10 (7)

G101 X10 Y20 (8)

X20 Y10. (9)

G100 Z5

G100 X20 Y45 Z2.

G101 Z-2 F40 (9)

G102 X70 Y45 R25 (10)

G102 X20 Y45 R25 (9)

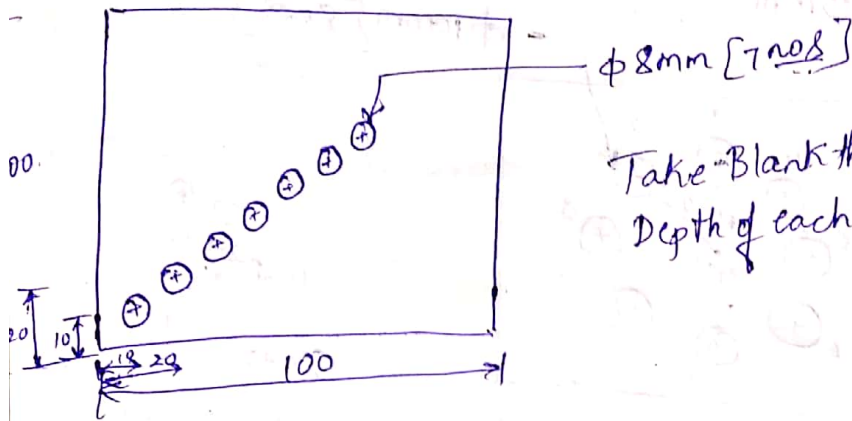
G100 Z5

G128 X0 Y0 Z0

M05

M130 I.

4. write a manual / mc part program to perform peck drilling operation [G183].



Take Blank thickness = 10mm
Depth of each hole 8mm.

[BILLET X100 Y100 Z10
O1247

G121 G194

G128 X0 Y0 Z0

M06 T0101

→ Drill bit φ 8mm

M03 S1000

G183 X10 Y10 Z-8 F40 Q4 R1 K1 - (1)

X20 Y20

-(2)

X30 Y30

-(3)

X40 Y40

-(4)

X50 Y50

-(5)

X60 Y60

-(6)

X70 Y70

-(7)

G180

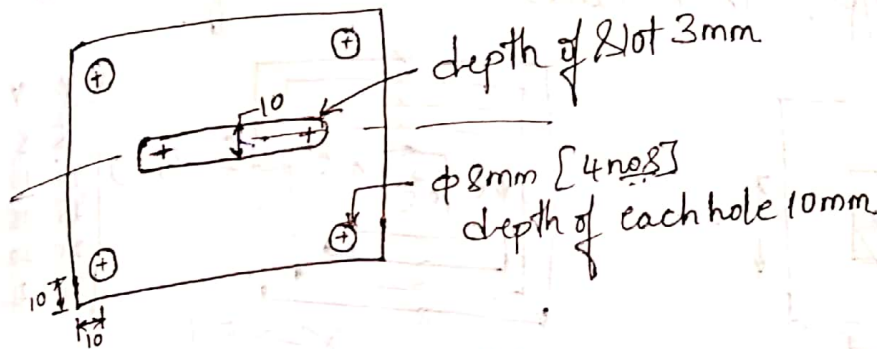
Peckdrilling Cancel

G128 X0 Y0 Z0

M05

T930]

6) Write a manual part program to perform Profile Cutting and drilling operation for the given Profile. Take BILLET SIZE 90X90X20 mm



[BILLET X90 Y90 Z20
O1245

G21 G294

G28 X0 Y0 Z0

M06 T01 → drill bit $\phi 8$ mm.

M03 S1500

G90 G00 X10 Y10 Z5

G183 ~~G01~~ X10 Y10 Z-10 F40 Q4 KI R1

X10 Y80

X80 Y80

X80 Y10.

G180

G28 X0 Y0 Z0.

M06 T02 → End mill $\phi 10$ mm

M03 S1000

G90 G00 X30 Y45 Z2

G701 Z-3 F40

G701 X70 Y45

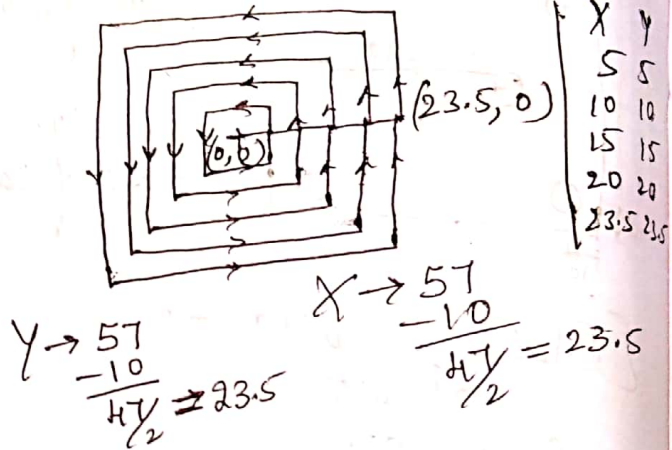
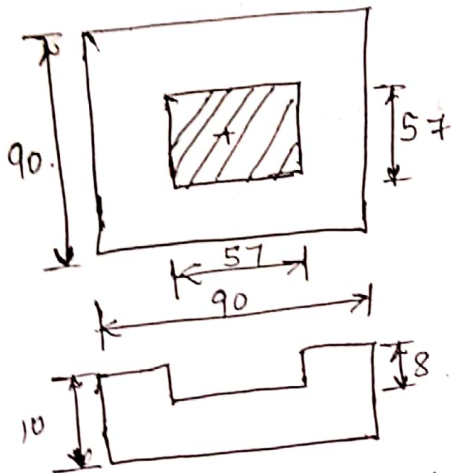
G700 Z5

G28 X0 Y0 Z0.

M05

M30]

7) write a manual part program to perform Square Pocket operation and workpiece Dimension 90x90x10mm, the pocket dimension 57x57x8mm and is located at the Centre of the w/p. use cutter diameter of 10mm.



G110 T1 X90 Y90 Z10
O1235

G121 G19 H

G128 X0 Y0 Z0

M06 T0101 -> Endmill ϕ 10mm

M03 S1000

G190 G100 Z5.

G101 X0 Y0 Z0 F30.

* M98 P008 I277
G100 Z5

G128 X0 Y0 Z0.

M105

M130.

O1277

G191 G101 Z-1 F30

G190 G101 X5 Y0

X5 Y5

X-5 Y5

X-5 Y-5

X5 Y-5

X5 Y0

X10 Y0

X10 Y10

X-10 Y10

X-10 Y-10

X10 Y-10

X10 Y0.

X15 Y0

X15 Y15

X-15 Y15

X-15 Y-15

X15 Y-15

X15 Y0.

X20 Y0

X20 Y20

X-20 Y20

X-20 Y-20

X20 Y-20

X20 Y0.

X23.5 Y0

X23.5 Y23.5

X-23.5 Y23.5

X-23.5 Y-23.5

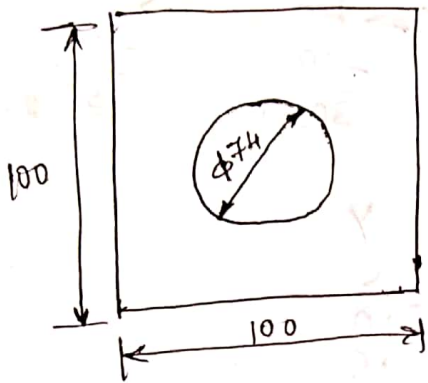
X23.5 Y-23.5

X23.5 Y0.

G101 X0 Y0

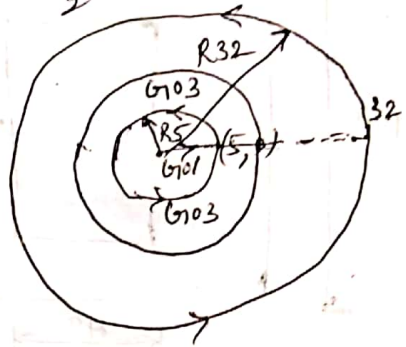
M99]

8) write a manual part program to perform circular pocket having Dimension R32 X 6mm. Take cutter diameter of 10mm.



$$X \rightarrow \frac{74}{2} - 10 = 32$$

X	R
5	5
10	10
15	15
20	20
25	25
30	30
32	32



[BILLET X100 Y100 Z10
O1T74

G21 G94

G28 X0 Y0 Z0.

M06 T0101 → Endmill ϕ 10mm

M03 S1000.

G70 X0 Y0 Z0 F35

M98 P0061234

G700 Z5

G28 X0 Y0 Z0

M05

M30.

O1234

G99 G701 Z-1 F30

G790 G701 X5 Y0

G703 X-5 Y0 R5

G703 X5 Y0 R5

G701 X10 Y0

G703 X-10 Y0 R10.

G703 X10 Y0 R10

G701 X15 Y0.

G703 X-15 Y0 R15

G703 X15 Y0 R15

G701 X20 Y0

G703 X-20 Y0 R20

G703 X20 Y0 R20

G701 X25 Y0

G703 X-25 Y0 R25

G703 X25 Y0 R25

G701 X30 Y0

G703 X-30 Y0 R30.

G703 X30 Y0 R30.

G701 X32 Y0

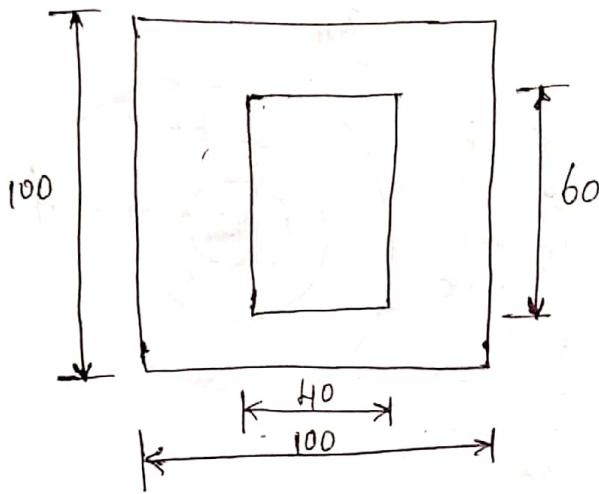
G703 X-32 Y0 R32

G703 X32 Y0 R32

G701 X0 Y0

M99]

9) write a manual part program for a Rectangular Pocketing as shown in figure. Take cutter diameter as 10mm and w/p centre as origin.



$$\begin{array}{r}
 X \rightarrow 40 \\
 -10 \\
 \hline
 30 \\
 \hline
 2 \\
 = 15
 \end{array}
 \qquad
 \begin{array}{r}
 Y \rightarrow 60 \\
 -10 \\
 \hline
 50 \\
 \hline
 2 \\
 = 25
 \end{array}$$

X	Y
5	5
10	10
15	15
15	20
15	25

[BILLET X100 Y100 Z10
O1774

G21 G94

G28 X0 Y0 Z0

M06 T0101 → End mill φ 10mm.

M03 S1000

G00 X0 Y0 Z0 F40

M98 P081245

G00 Z5

* G28 X0 Y0 Z0

M05

M30.

O1774

G91 G101 Z-1 F40

G90 G101 X5 Y0

X5 Y5

X-5 Y5

X-5 Y-5

X5 Y-5

X5 Y0

X10 Y0

X10 Y10

X-10 Y10

X-10 Y-10

X10 Y-10

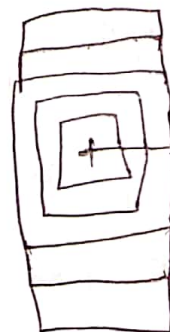
X10 Y0

X15 Y0

G101 X0 Y0

M99]

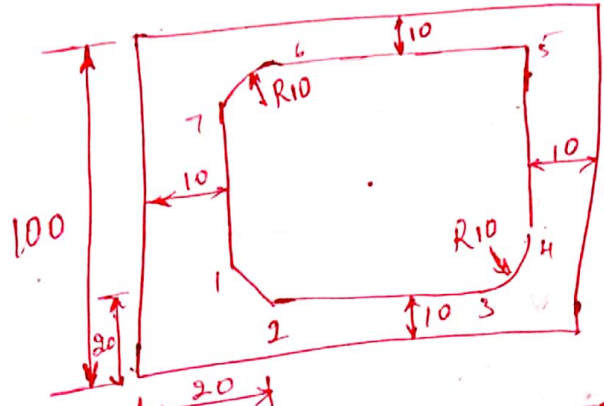
Tool Path
Movement



2

10) Write an MC Program for the given profile to perform Endmilling operation. Take cutter diameter 30mm.

25

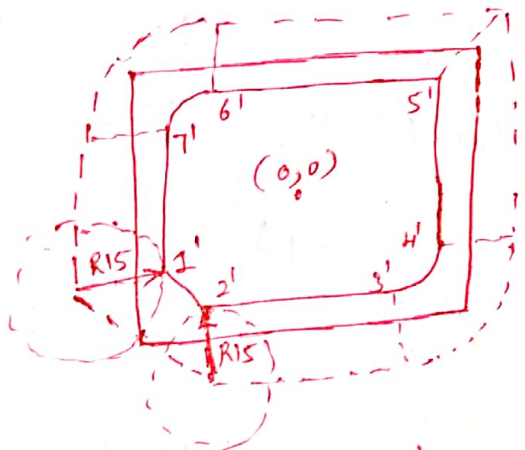


- 1 (-40, -30)
- 2 (-30, -40)
- 3 (30, -40)
- 4 (40, -30)
- 5 (40, 40)
- 6 (-30, 40)
- 7 (-40, 30)



[BILLET X100 Y100 Z10
O1145

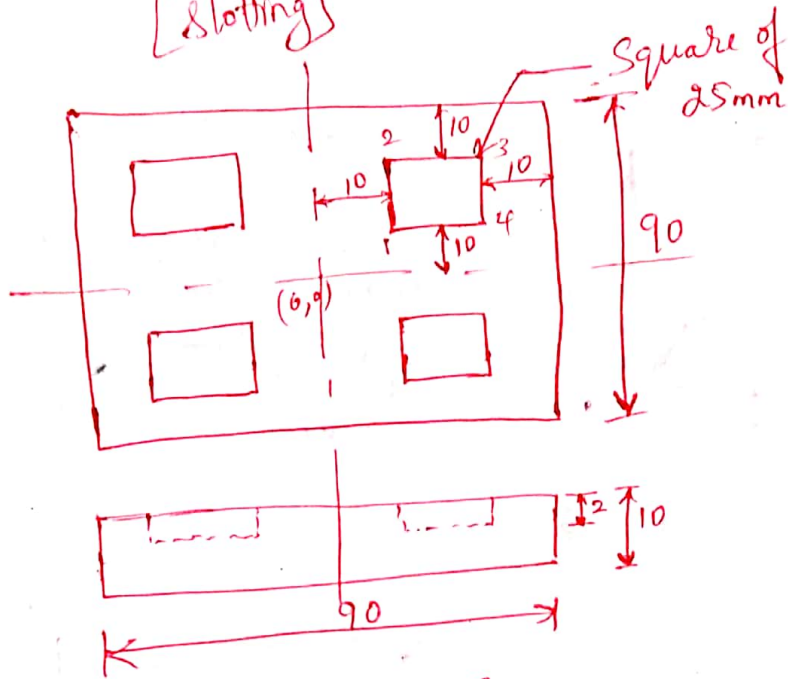
```
G721 G94
G728 X0 Y0 Z0
M06 T0101
M03 S500
G190 G100 X-55 Y-30 Z2
G101 Z-2 F40 (1)
X-30 Y-55 (2)
X 30 Y-55 (3)
G103 X55 Y-30 R25 (4)
G101 X55 Y55 (5)
X-30 Y55 (6)
G103 X-55 Y30 R25 (7)
G101 X-55 Y-30 (1)
G100 Z5
G728 X0 Y0 Z0
M05
M30]
```



- 1' (-55, -30)
- 2' (-30, -55)
- 3' (30, -55)
- 4' (55, -30) R25
- 5' (55, 55)
- 6' (-30, 55)
- 7' (-55, 30) R25

11) Write a manual part program to perform mirror operation for the given profile.

[Slotting]



- 1 (10, 10)
- 2 (10, 35)
- 3 (35, 35)
- 4 (35, 10)

[BILLET X 90 Y 90 Z 10
01774

G21 G94

G28 X0 Y0 Z0

M06 T0101 → Endmill of 10mm

M03 S1000

G90 G01 X10 Y10 Z0 F40

M98 P021234

G00 Z5

M70

→ X mirror ON (All +Y → -Y)

G01 X10 Y10 Z0 F40

M98 P021234

G00 Z5

M71

→ Y mirror ON (All +X → -X)

G01 X10 Y10 Z0 F40

M98 P021234

G00 Z5

M80

→ X mirror OFF [All -Y → +ve Y]

G01 X10 Y10 Z0 F40

M98 P021234

G00 Z5

M81

→ Y mirror OFF (All -X → +ve X)

G128 X0 Y0 Z0

M05

M30

O1234

G191 G101 Z-1 F40

G190 G101 X10 Y35 (2)

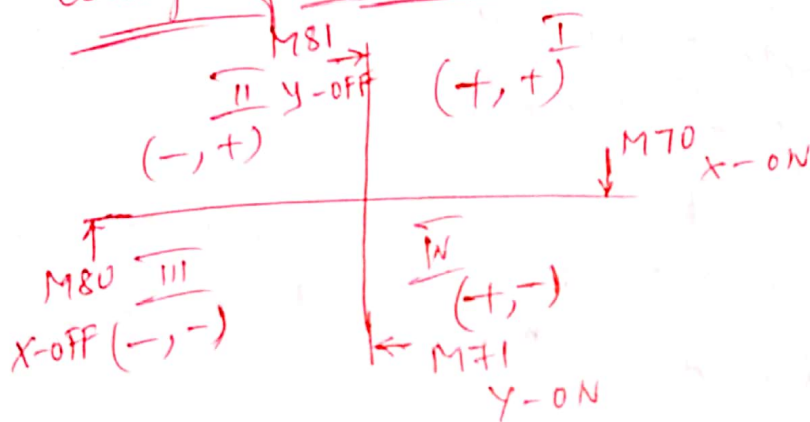
X 35 Y35 (3)

X 35 Y10 (4)

X10 Y10 (5)

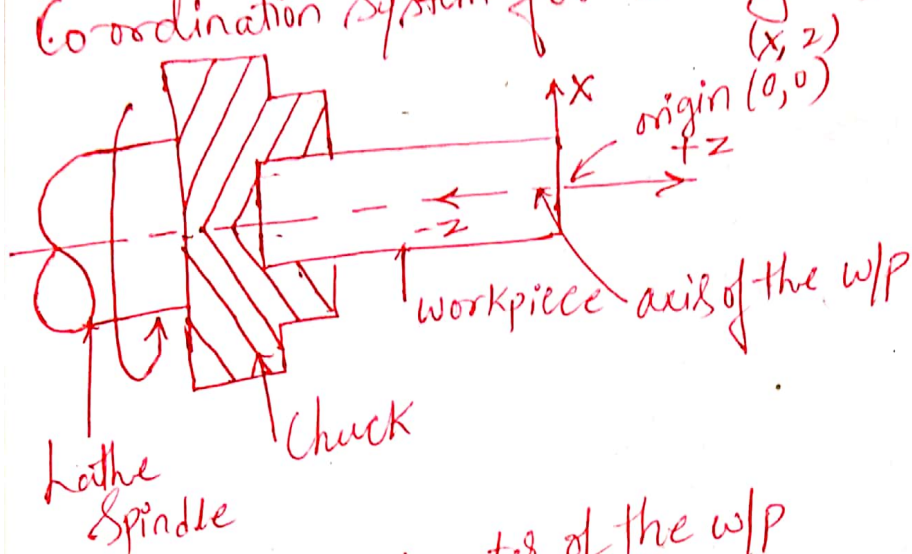
M99]

Concept of Mirror operation



Turning :-

Coordination System for turning operation.



where $x \rightarrow$ Diameter of the w/p
 $z \rightarrow$ Length of the w/p.

In turning operations w/p will have rotational motion and tool is held stationary on the tool post.

Cutting Parameters :-

1. Depth of Cut [DOC] :- It is the perpendicular distance b/w machined and un-machined surface. unit: mm.

2. Feed (mm/min @ mm/rev) :- F

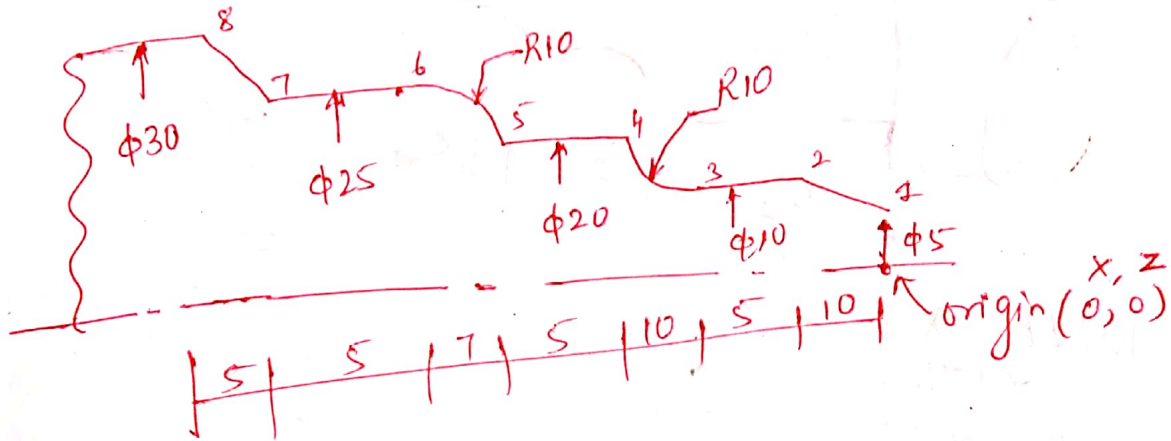
Distance travelled by the tool per minute @ per revolution.

3. Spindle Speed (rpm) :- S

Number of rotation made by the tool / workpiece per minute.

1. Write a manual Part program to perform turning operation without canned cycle take cutting tool as external turn of nose radius 0.8mm.

(a)
Linear and circular interpolation.



[BILLET X30 Z50
01245

G721 G798 mm; mm/min

G728 U0 W0

M06 T01

M03 S1500

~~G700~~ X30 Z2 initial safe position.

G700 X5 Z0 (1)

G701 X10 Z-10 F40 (2)

G701 X10 Z-15 (3)

G702 X20 Z-25 R10 (4)

G701 X20 Z-30 (5)

G703 X25 Z-37 R10 (6)

G701 X25 Z-42 (7)

X30 Z-47 (8)

G700 X30 Z2

G728 U0 W0

M05 M30

1(5, 0)

2(10, 10)

3(20, -15)

4(20, -25)

5(20, -30)

6(25, -37)

7(25, -42)

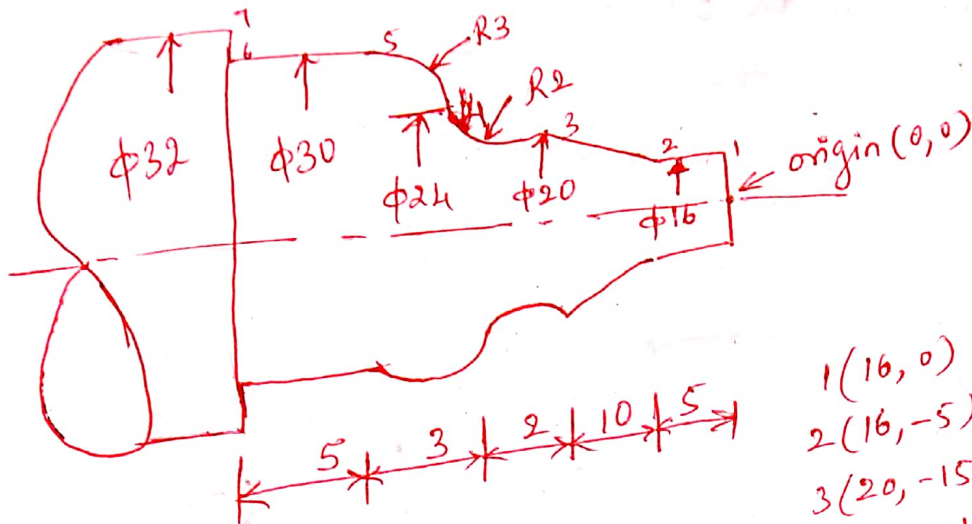
8(30, -47)



Reference position of tool.

→ Ext turn of nose radius 0.8mm

2. Write a manual part program to perform Multiple turning operation by using canned cycle.



- 1 (16, 0)
- 2 (16, -5)
- 3 (20, -15)
- 4 (24, -17)
- 5 (30, -20)
- 6 (30, -25)
- 7 (32, -25)

[BILLET X 32 Z 30

01748

G21 G98

G28 U0 W0

M06 T01

M03 S1200

G00 X32 Z2

G71 U0.5 R1

G71 P10 Q20 U0.5 W0.5 F40 → P10 Q20 :- Profile starting & ending no

X10 G00 X16 Z0 (1)

G01 X16 Z-5 (2)

X20 Z-15 (3)

G02 X24 Z-17 R2 (4)

G03 X30 Z-20 R3 (5)

G01 X30 Z-25 (6)

G01 X32 Z-25 (7)

X20 G00 X32 Z2

G70 P10 Q20

G28 U0 W0

M05
M30

mm; mm/min

→ Ext dia 0.8mm

→ initial safe position of tool

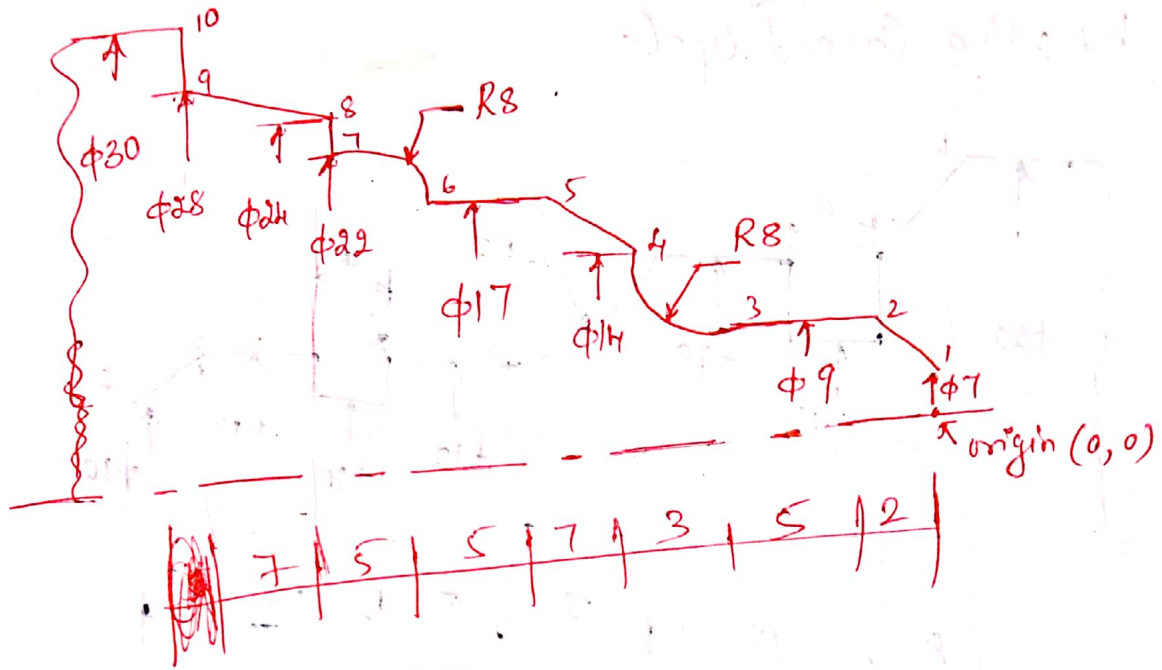
→ U0.5 :- Amount of material removed in X-axis (0.5mm)

R :- Retain (1mm)

→ P10 Q20 :- Profile starting & ending no

U0.5 W0.5 :- Amount of stock maintained on the w/p for finishing cycle

3. Write a manual part program to perform Multiple turning operation by using canned cycle [G71] & G70]



[BILLET X 30 Z 40
08989

G21 G98

mm; mm/min

G28 U0 W0

M06 T01

M03 S1800

G20 X30 Z2

G71 U0.5 R1

G71 P10 Q20 U0.5 W0.5 F40

M10 G20 X7 Z0 (1)

G20 X9 Z-2 (2)

G20 X9 Z-7 (3)

G20 X14 Z-10 R8 (4)

G20 X17 Z-17 (5)

X17 Z-22 (6)

G20 X22 Z-27 R8 (7)

G20 X24 Z-27 (8)

X28 Z-34 (9)

1 (7, 0)

2 (9, -2)

3 (9, -7)

4 (14, -10) R8

5 (17, -17)

6 (17, -22)

7 (22, -27) R8

8 (24, -27)

9 (28, -34)

10 (30, -34)

X30 Z-34 (10)

N20 G20 X30 Z2

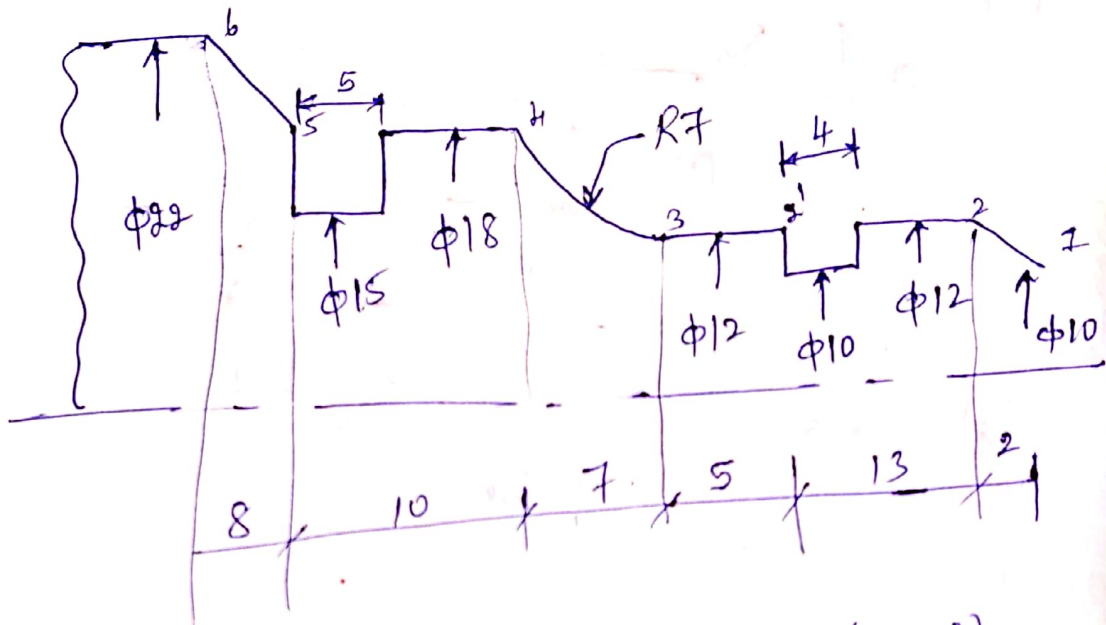
G70 P10 Q20

G28 U0 W0

M05

M30]

A.) Write a manual part program to perform External grooving operation for the given profile by using Canned cycle



{ BILLET X22 Z50
01247

G121 G98

G128 U0 W0

M06 T0101

M03 S1000

G100 X22 Z2

G171 U0.5 R1

G171 P10 Q20 U0.5 W0.5 F40

N10 G00 X10 Z0 (1)

G101 X12 Z-2 (2)

X12 Z-20 (3)

G102 X18 Z-27 R7 (4)

G101 X18 Z-37 (5)

G101 X22 Z-45 (6)

N20 G00 X22 Z2

1(10, 0)

2(12, -2)

3(12, -20)

4(18, -27)

5(18, -37)

6(22, -45)

Grooving
1'(12, -15)

5(18, -37)

G170 P10 Q20

G128 U0 W0

M06 T0202

M03 S1200

G100 X12 Z-15

G175 R1

G175 X10 Z-14 P250 Q500 F40

G128 U0 W0

G100 X18 Z-37

G175 R1

G175 X15 Z-35 P250 Q500 F40

G128 U0 W0

M05

M30]

Ext groove [3mm width]

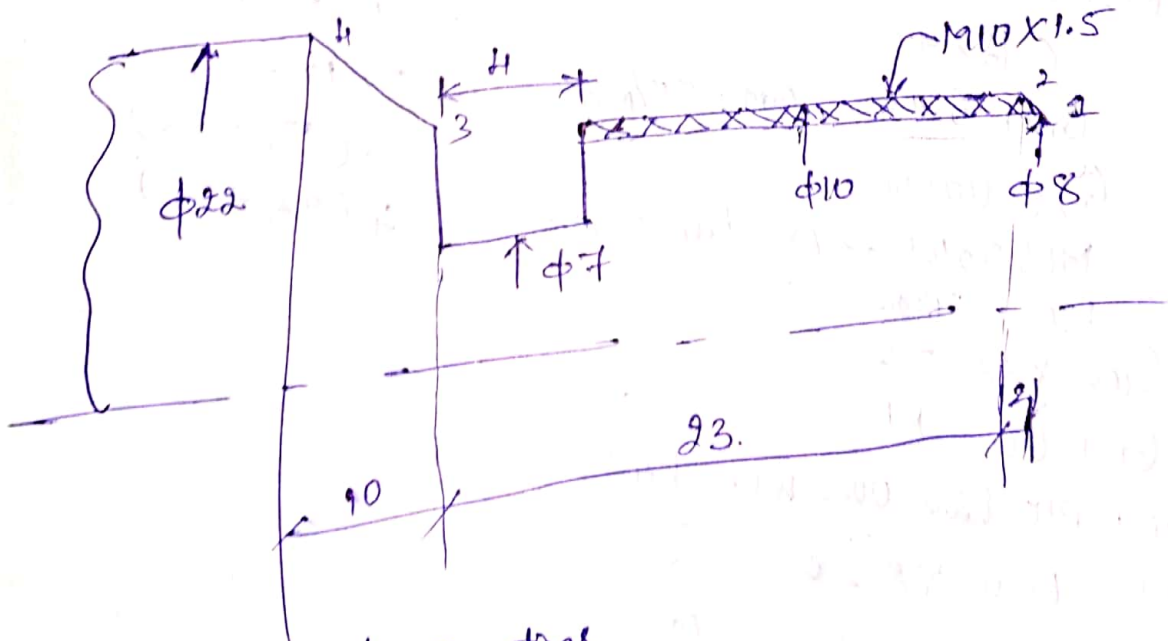
initial position of the grooving tool

→ Relief for the tool.

P250 and Q500 are the movement of tool along X & Z direction in 'H'.

initial position of the grooving tool.

5) Write a part program to perform threading operation on the component shown in figure



Soln :- Sequence of operations

G171 → Rough turning

G170 → Finishing

G175 → External grooving

G176 → External threading

Threading Calculations:- for v-thread

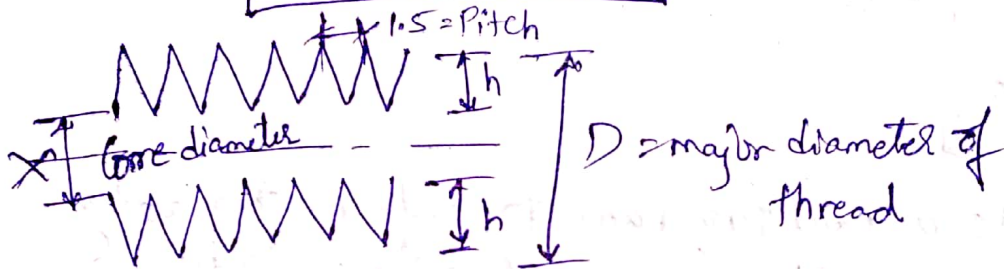
Height of the thread

$$\begin{aligned} h &= P \times 0.61343 \\ &= 1.5 \times 0.61343 \\ &= 0.920 \text{ mm} \end{aligned}$$

$$h = 920 \mu = P$$

$$\begin{aligned} \text{Core diameter} &= \text{major diameter} - 2h \\ &= 10 - 2 \times 0.920 \end{aligned}$$

$$X = 8.16 \text{ mm}$$



[BILLET X22 Z40

01289

G71 G98 mm; mm/min

G28 U0W0

M06 Tolol \rightarrow Ext turn 0.8mm

M03 S1200

G700 X22 Z2

G71 U0.5 R1

G71 P10 Q20 U0.5 W0.5 F40

N10 G700 X8 Z0 F1

G701 X10 Z-2 (2)

G701 X10 Z-25 (3)

G701 X22 Z-35 (4)

N20 G700 X22 Z2

1(8,0)

2(10,-2)

3(10,-25)

4(22,-35)

G70 P10 Q20

G28 U0W0

M06 T0202 Ext Groove (3mm)

M03 S800

G200 X10 Z-25 initial position of grooving tool

G75 R1

G75 X7 Z-24 P250 Q500 F10

G28 U0W0

M06 T0303 (Ext threading tool L.H thread angle 60°)

M03 S1000

G100 X10 Z0 initial position of threading tool.

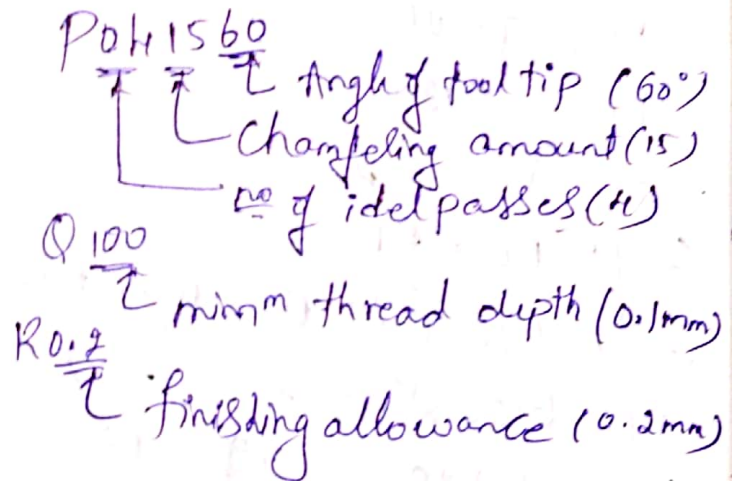
G76 P041560 Q100 R0.2

G76 X8.16 Z-21 P920 Q200 F1.5

G28 U0W0

M05

M30J



X8.16
↑ Core dia / minor dia of thread

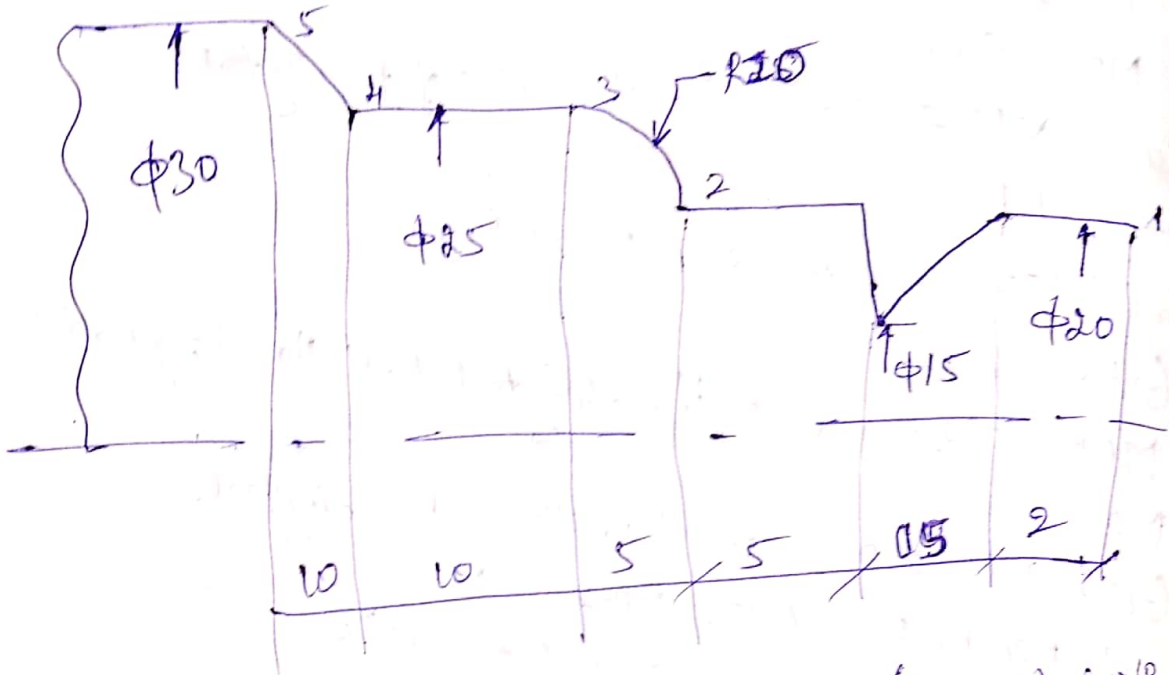
Z-21
↑ Length of thread

P920
↑ height of thread in 'el'

Q200
↑ depth of cut in 1st cut (mm)
0.2

F1.5
↑ Lead of thread on M/c tool (1.5mm)

6) Write a manual part program to Box turning / taper turning operation for the given profile



[BILLET X 30 Z 42

G121 G08

G28 U0 W0

M06 T0101

M03 S1200

G00 X30 Z2

G71 U0.5 R1

G71 P10 Q20 U0.5 W0.5 F40

N10 G00 X20 Z0 (1)

G01 X25 Z-17 (2)

G03 X25 Z-27 R20 (3)

G01 X25 Z-32 (4)

X30 Z-37 (5)

N20 G00 X30 Z2

G70 P10 Q20

1(20, 0) \rightarrow 10

2(20, -17)

3(25, -22)

4(25, -32)

5(30, -42)

\rightarrow 5

1(20, 0)

2(20, -12)

3(25, -17)

4(25, -27)

5(30, -37)

G128 U0 W0
 G100 X20 Z-2 initial position for taper turning tool
 G190 X20 Z-0.7 R0 F10
 X19 R0.5
 X18 R1
 X17 R1.5
 X16 R2
 X15 R2.5
 G100 X30 Z2
 G128 U0 W0
 M05
 M30

$Z = 0.7$ Length of taper from origin
 $R \rightarrow$ taper amount

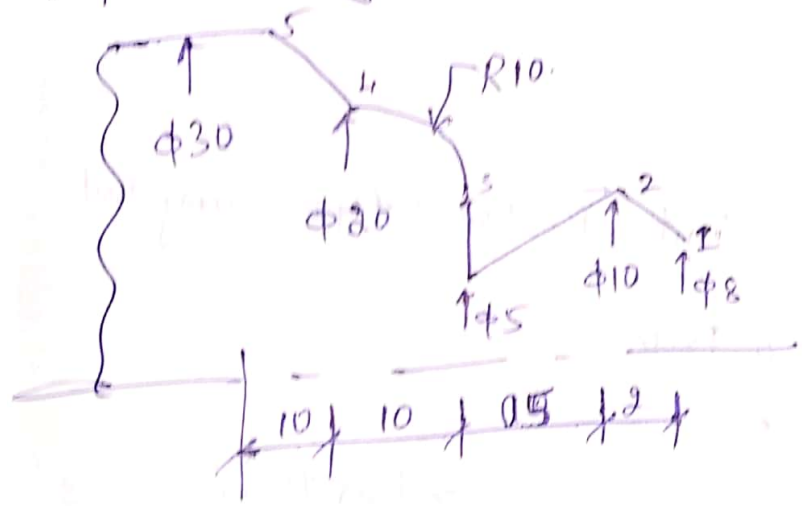
$$\tan \alpha = R = \frac{D-d}{2 \times L}$$

$D \rightarrow 20$
 $d \rightarrow 15$
 $L \rightarrow 0.5$

$$R = \frac{20-15}{2 \times 0.5} = 5$$

$R = 0.5$

ii) Write a part program for Multiple turning operation for the Component shown in figure by using taper turning cycle.



$L \rightarrow 0.5$
 1(8, 0)
 2(10, -2)
 3(10, -7)
 4(20, -17)
 5(30, -24)
 $L \rightarrow 10$

Ex 10: taper amount (R)

$D \rightarrow 10$
 $d \rightarrow 5$
 $L \rightarrow 5$

$$\tan \alpha = R = \frac{D-d}{2 \times L}$$

$$= \frac{10-5}{2 \times 5}$$

$$R = 0.5$$

1(8, 0)
 2(10, -2)
 3(10, -12)
 4(20, -22)
 5(30, -32)

[BILLET X30 Z35

01289

G21 G98

G28 U0 W0

M06 T0101

M03 S1500

G00 X30 Z2

G71 U0.5 R1

G71 P10 Q20 U0.5 W0.5 F40

N10 G00 X8 Z0 (1)

G01 X10 Z-2 (2)

X10 Z-07 (3)

G03 X20 Z-27 R10 (4)

G01 X30 Z-37 (5)

N20 G00 X30 Z2

G70 P10 Q20

G28 U0 W0

G00 X10 Z-2

initial position of taper turning tool

G90 X10 Z-07 R0 F40

X9 R0.5

X8 R1.0

X7 R1.5

X6 R2

X5 R2.5

G00 X30 Z2

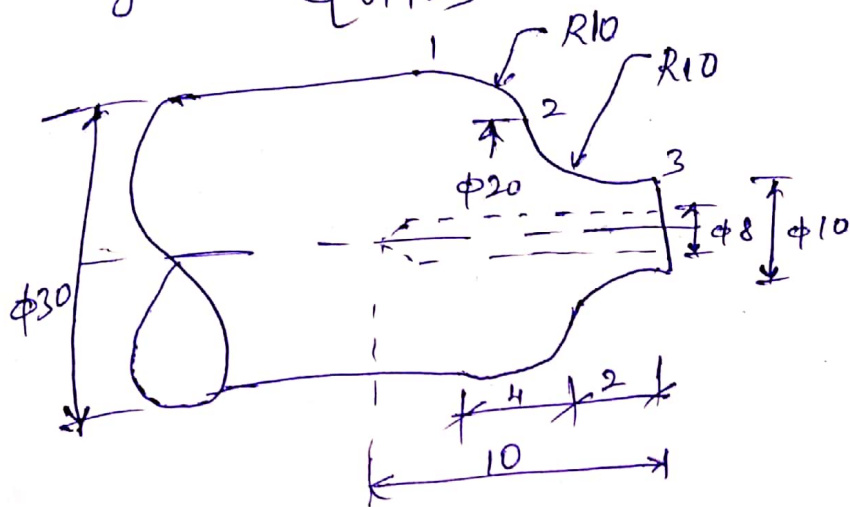
G28 U0 W0

M05

M30]

G90 → Box turning cycle/
Taper turning cycle

8) write a Part Program for Multiple Drilling operation for the component shown in figure using Facing and Drilling cycle. [G74] [G72]



[BILLET $\times 30$ Z20
01287

G21 G98

G28 U0 W0

M06 T0101

M03 S2000

G700 X30 Z2

G72 W0.5 R1

G72 P10 Q20 U0.5 W0.5 F40

N10 G700 X30 Z-6 (1)

G700 X20 Z-2 R10 (2)

G703 X10 Z0 R10 (3)

N20 G700 X30 Z2

G770 P10 Q20

G28 U0 W0

M06 T0202 \rightarrow Tientre drill $\phi 8$ mm

M03 S1000

G700 X0 Z2

G74 R1

G74 X0 Z-10 Q500 R1 F15

G728 U0 W0

M05 M30]

1(30, -6)

2(20, -2)

3(10, 0)

G74 R1 \rightarrow Return amount

Z-10 \rightarrow depth of hole

Q500 \rightarrow depth of cut in Z direction (0.5mm)

R1 \rightarrow Relief for tool @ the cutting bottom

F15 \rightarrow feedrate (mm/min)

1.) CIM:- Computer Integrated Manufacturing

Automation:-

It is defined as technology concerned with mechanical, electrical, electronics and Computer based system in order to control the production by means of computer integrated system.

2.) NC:- Numerical Control.

It involves with G-codes, M-codes, Numerical, symbols which describe the motion of the tool to perform operation on machine tool. It is a form of programmable automation.

3.) CNC:- Computer Numerical Control.

In this CAD drawing is constructed and movement of tool is defined so that the computer will control the motion of the tool and generate programme.

Components of CNC:-

1.) Computer / Monitor

2.) Machine Control Unit [MCU]

It transfer the part programme into actual Machining on Machine tool

3.) Machine tool:-

where actual Machining will occur

For taper turning / Box turning cycle
[G90] G90 X10 Z-30 R0 F30
 $\tan \alpha = \frac{D-d}{2L} = R$ ↑
Taper amount
R = taper amount

4) ~~Automation~~:-

Software using:-

See NC Mill 6.0v

See NC turn 6.0v

Types of Automation:-

1. Fixed automation
2. Programmable Automation
3. Flexible Automation.

4) CIM:- It is an Manufacturing approach of using Computer to control the entire production process.

It integrate electrical, electronic, computer and mechanical system to exchange information to control the production system.

5) NC Machines

- Run by Servomotors, encoders, ball screw
- make use of punched tapes.
- It cannot import CAD files
- It cannot use feedback signal
- In order to modify the Programme, the tape have to be changed.
- Highly Skilled operator are required

CNC Machines

- Run by computer [PC's]
- Make use of floppy disk, stored programs.
- It can import CAD files
- It make use of feedback signal
- Programme can be easily modify.
- Less Skilled operator are required

Preparatory Codes [G-Codes]

It refers to control of motion of the tool and which describe some specific operation.

Ex:- G00 - rapid traverse of tool
G01 - linear traverse of tool
G71 - Rough turning cycle
G70 - finishing cycle

7) Miscellaneous Codes [M-Codes]

It refers to machine control rather than control of motion of tool.

Ex:- M03 - Spindle rotate in C.W.
M05 - Spindle off
M06 - Tool change

8) G-Codes

G00 - rapid traverse of tool

G01 - linear

G02 - Circular traverse (C.W)

G03 - " " (C.C.W)

G04 - Dwell. [Tool resides for a certain period to get flat surface during drilling operation]

G90 - Inches unit

G91 - Metric unit

G28 - Reference position of tool

G98 - Feed (mm/min)

G83 - Peck drilling

G80 - Peck drilling cancel

G70 - finishing cycle

G71 - Rough turning cycle

G72 - Facing cycle

G73 - ~~Centre drill~~ High peck drilling

G74 - Centre drill

G75 - External Grooving

G76 - External Threading

X, Y, Z: Primary

Co-ordination

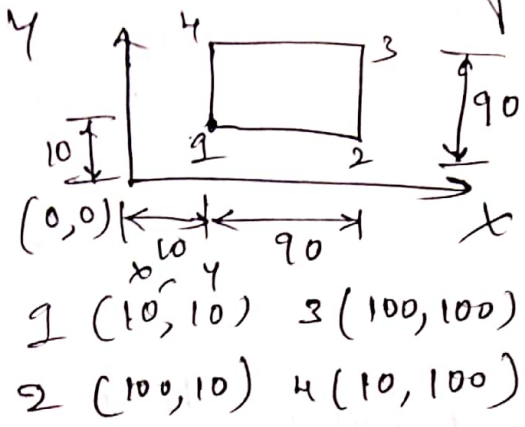
System.

U, V, W:

Secondary Co-ordination System

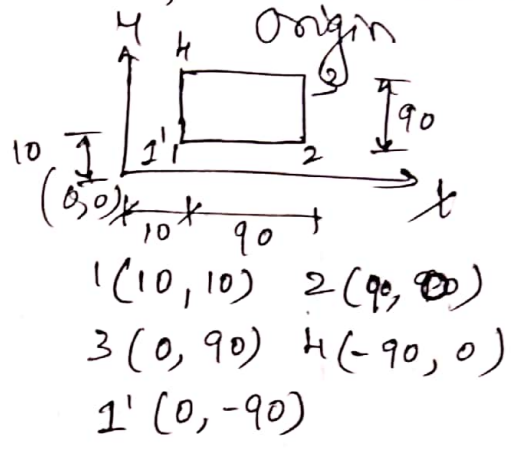
(2)

9) Incremental method of programming:-
 G10:- Co-ordinates are obtained from the fixed origin.



Incremental method of programming

G11:- Co-ordinates are obtained taking previous location as



10) Basic NC Motions:-

- 1) Linear Interpolation G00, G01
- 2) Circular Interpolation G02 and G03

3) Point to Point [PTP] Motion

G03.

Miscellaneous Codes:-

- M00 - optional program stop
- M30 - Programme end/End of programme
- M05 - Spindle off
- M03 - Spindle rotate in C.W
- M04 - ——— 11 - C.C.W
- M06 - tool change
- M08 - Coolant ON
- M09 - Coolant OFF
- M98 - Sub Programm Call
- M99 - End of Sub Program Call

S - Spindle Speed (rpm)

F - Feed (mm/min)

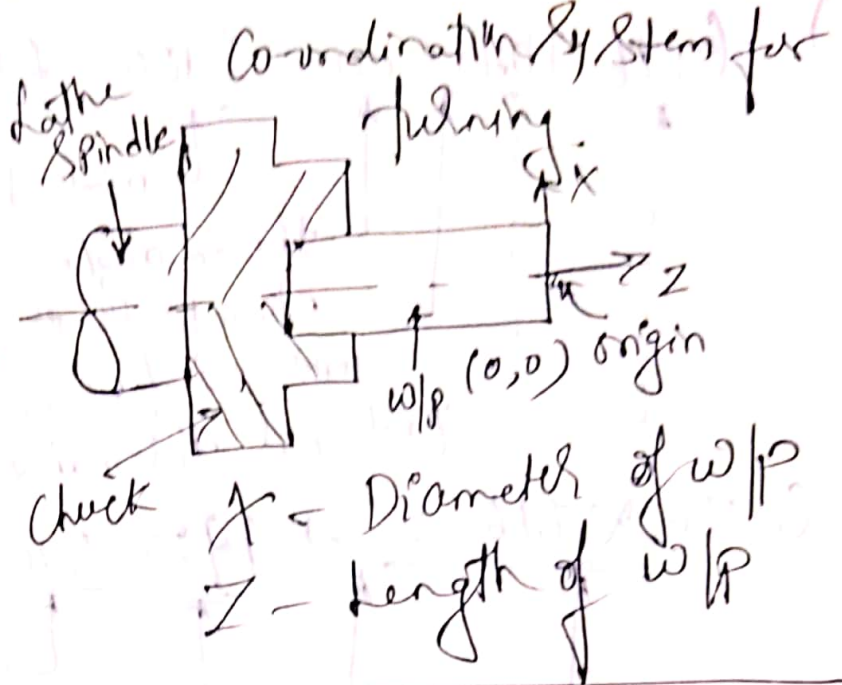
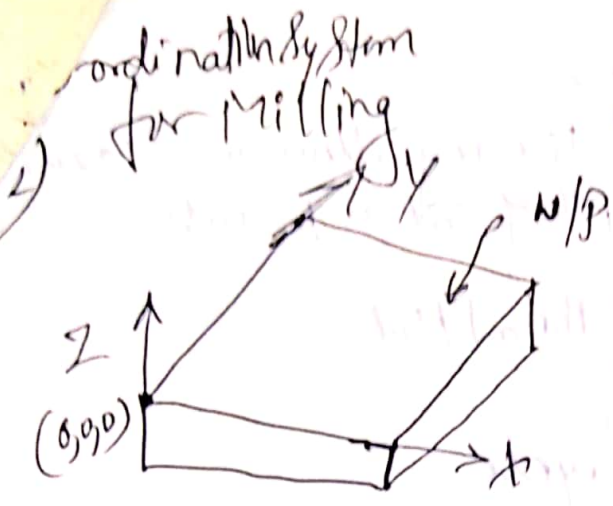
T - tool no

Z - thickness of w/p depth

X, Y - Co-ordination sys

In case of turning:-

- X - diameter of w/p
- Z - Length of w/p



3) G71 - Rough turning

G71 U0.5 R1 $\frac{R}{E}$ Return of tool
 ↳ @ wt rate material has to be removed

G71 P10 Q20 U0.5 W0.5 $\frac{F40}{E}$ feedrate (mm/min)
 ↳ amount of stock maintained on W/P for finishing cycle

↳ Profile ending no.
 ↳ Profile starting no.

N10 - Profile starting Block no
 N20 - Profile ending Block no

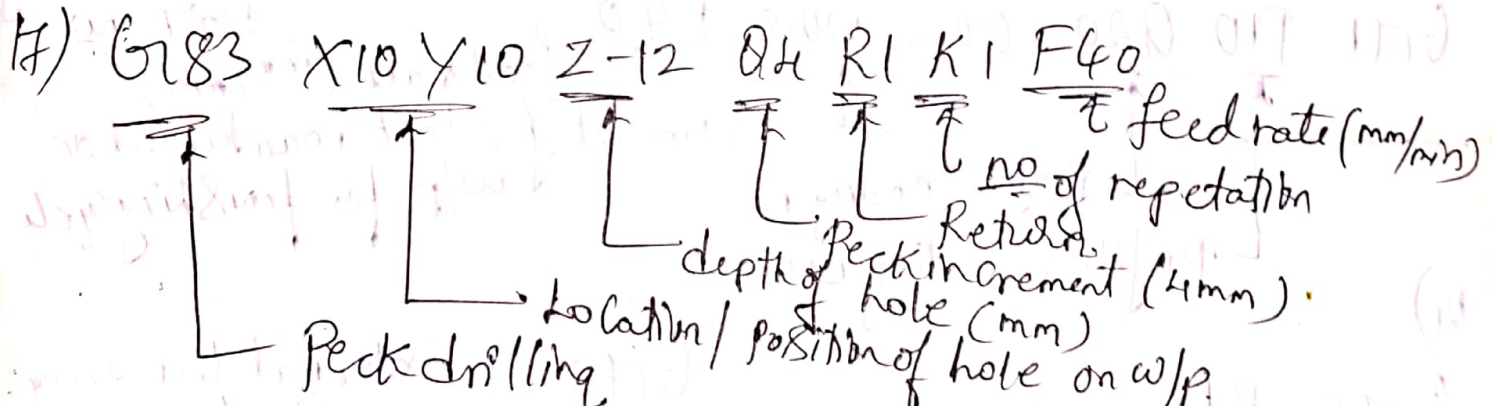
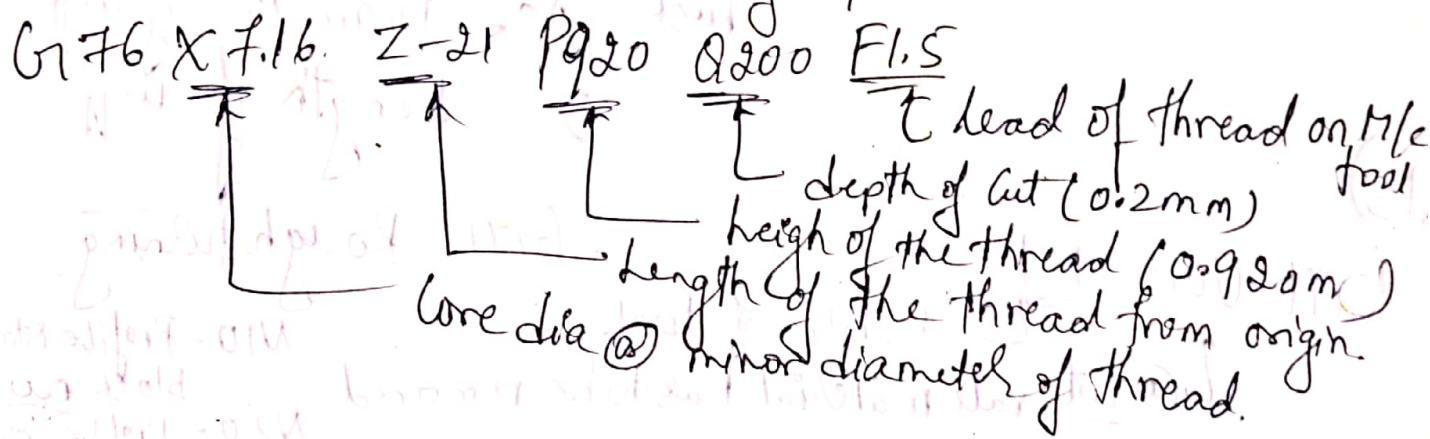
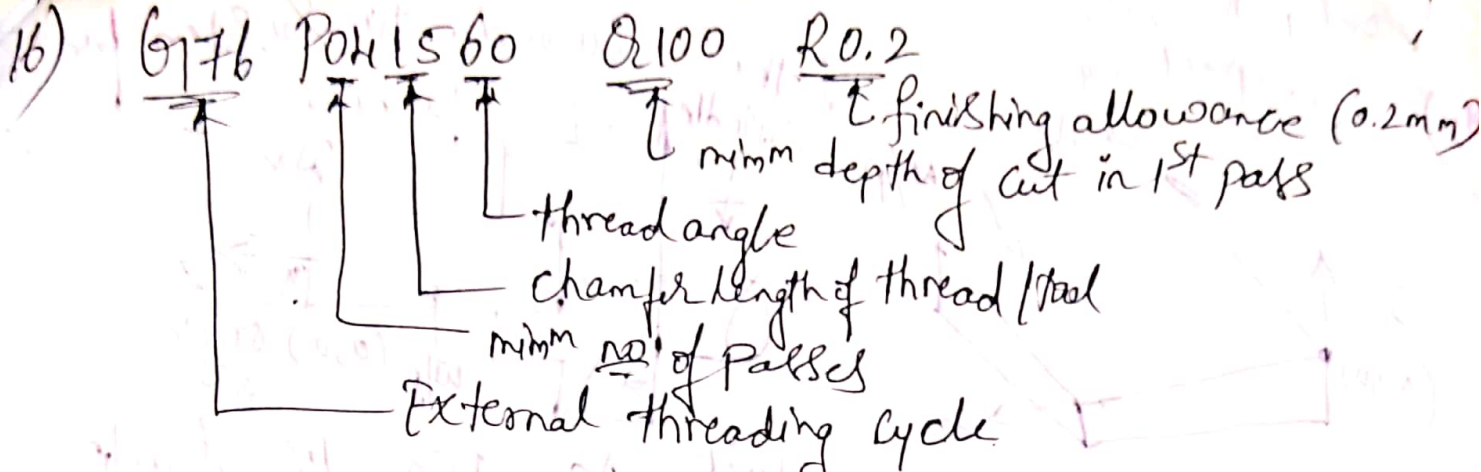
4) G75 - External grooving cycle

G75 R1 $\frac{R}{E}$ Relief for tool (Sec)

G75 X5 Z-21 P250 Q500 F40
 ↳ movement of Grooving tool in z-direction (mm)
 ↳ Dimension from the origin in x-direction (mm)
 ↳ Required diameter of groove

5) G70 - Finishing cycle

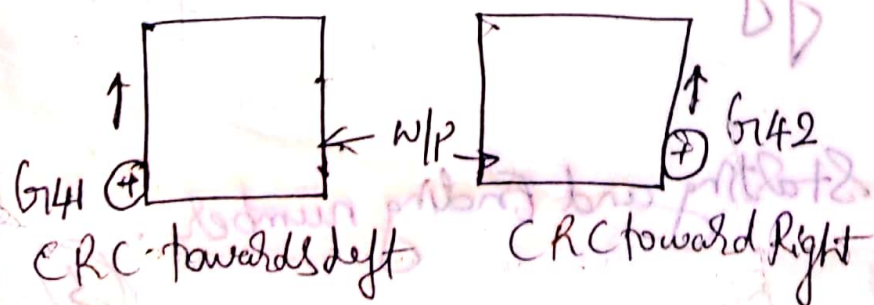
G70 P10 Q20 $\frac{R}{E}$ Profile starting and Ending number



G180 - Peck drilling cancel.

CRC :- Cutter Radius Compensation
used to obtain exact Profile
Dimension on w/p.

G140 - CRC Cancel



Types of error :-

Syntax error :-

- It refer to improper deformation of Code in the Programme
ex- If G03 line R is not defined.
G01 line F is not defined

Omission error :-

omitting decimal values

Setup error :-

wrong entry of Dimension value in Blank.