

(3 Hours)

[Total Marks : 100

N.B. (1) Question No. 1 is **compulsory**.(2) Attempt any **four** questions out of remaining **six** questions.(3) Assume suitable **data** wherever **necessary**.(4) **Figures** to the **right** indicate **full marks**.

1. (a) Explain mechatronics system used for domestic cloth washing machine using following components :— **5**
- Mechanical systems
 - Electrical systems
 - Computer systems
 - Sensors and actuators
 - Logic.
- (b) What are the parameters you will consider for selection of an actuation system for any Physical Industrial System ? **5**
- (c) Determine K_p , K_v and K_a (position, velocity and actuation errors respectively) for a system with, $G(s) = \frac{100}{s(s+0.5)(4-s)(s+1000)}$ and $H(s) = 1$. **5**
- (d) Write short note on Variable Reluctance Stepper Motor. **5**
2. (a) How would you classify the control systems based on the TYPE of system ? A unity feedback system has, $G(s) = \frac{40(s+2)}{s(s+1)(s+4)}$. Determine, **10**
- Type of the system
 - All error co-efficients
 - Error for ramp input with magnitude 4.
- (b) Explain the functional block diagram of 8051. **10**
3. (a) Design a pneumatic circuit for work clamping on a milling table, the sequence is : A^+ , B^+ , B^- , A^- . **10**
- (b) How DAC is specified ? Explain interfacing of DAC with block diagram. **10**
4. (a) The unit impulse response of a certain system is found to be e^{-4t} . Determine its transfer function. **10**
- (b) Construct an electro pneumatic circuit with following conditions : **10**
- A transport cylinder A should automatically reciprocate to and fro. But another cylinder B is to be actuated by cylinder A just after it starts its forward motion and the cylinder B should retract before the cylinder A completes its forward journey after which cylinder A returns.

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5. (a) Explain the factors to be considered for selection of PLC for a control system. **10**
 What is the use of ladder logic diagram in PLC programming ?
 (b) Sketch the root locus for the system with : **10**

$$G(s)H(s) = \frac{K(s+4)}{s(s^2+2s+2)}.$$

6. (a) A unity feedback control system has $G(s) = \frac{80}{s(s+2)(s+20)}$. Draw the Bode **10**
 plot. Determine G.M., P.M., ω_{gc} and ω_{pc} . Comment on stability.
 (b) Explain interfacing of :— **10**
 (i) Stepper motor
 (ii) LCD display.

7. (a) A second order system is given by $\frac{C(s)}{R(s)} = \frac{25}{s^2+6s+25}$. Find its rise time, **10**
 peak time, peak overshoot and settling time if subjected to unit step input. Also
 calculate expression for its output response.
 (b) Compare : **10**
 (i) Hydraulic and pneumatic systems
 (ii) Routh and Hurwitz criterions.
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