

- N.B. (1) Question No. 1 is compulsory and solve any four from remaining six questions.
 (2) Figures to the right indicate full marks.
 (3) Assume data if necessary, and give justifications

1. (a) Explain rotate instructions of PIC 18 F controller. 5
 (b) Explain flag register of 8086 processor. 5
 (c) Explain MOVLW and COMF instructions in PIC 18 F. 5
 (d) Explain need for handshaking signal used with various modes of 8255 PPI. 5
2. (a) Explain working and interface of numeric data coprocessor 8087 with 8086. 10
 (b) What are the different function blocks in 8259, Programmable Interrupt Controller ? 10
 Explain their role in the process of interrupt handling.
3. (a) Discuss in brief, the memory organization of PIC 18 F microcontroller. What is the purpose of processor stack ? 10
 (b) Give two examples of each type of addressing modes in 8086 given below : 10
 (i) Direct Addressing
 (ii) Based Addressing
 (iii) Implicit Addressing
 (iv) Immediate Addressing
 (v) Based and Indexed Addressing.
4. (a) Draw and explain 8086 system operating in maximum mode. 10
 (b) Write a program to perform 32 bit x 32 bit multiplication. 10
5. (a) Explain different addressing modes of PIC 18 F. 10
 (b) Draw timing diagrams for minimum mode of 8086-- 10
 (i) Read Bus Cycle
 (ii) Write Bus Cycle.
6. (a) Explain any two applications of Timer in PIC 18 F and write a program to calculate delay of 100 μ s (Frequency is 40 MHz). 10
 (b) Design 8086 based micro computer system using minimum mode with following specifications : 10
 (i) CPU working at 5 MHz
 (ii) 32 kB SRAM (16 kB x 8 devices)
 (iii) 32 kB EPROM (8 kB x 8 devices)
 Draw neat schematic and use exhaustive decoding.
7. Write short notes on :-
 (a) PIC 18 Reset 5
 (b) Comparative study of salient features of 8086 and Pentium 5
 (c) DMA Controller modes 5
 (d) Mixed Language programming. 5