



IV. a) Describe the cause, effects and control measures of water pollution.

OR

b) Explain the role of individual in disaster management.

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V. a) "Earth is over populated". Do you agree with the statement? Justify.

OR

b) Explain the role of Information Technology in environment and human health.

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Reg. No. :

Name :

VI Semester B.Tech. Degree (Regular/Supplementary/Improvement –
Including Part Time) Examination, May 2014

(2007 Admn. Onwards)

PT2K6/2K6 EC/AEI 602 : CONTROL SYSTEMS

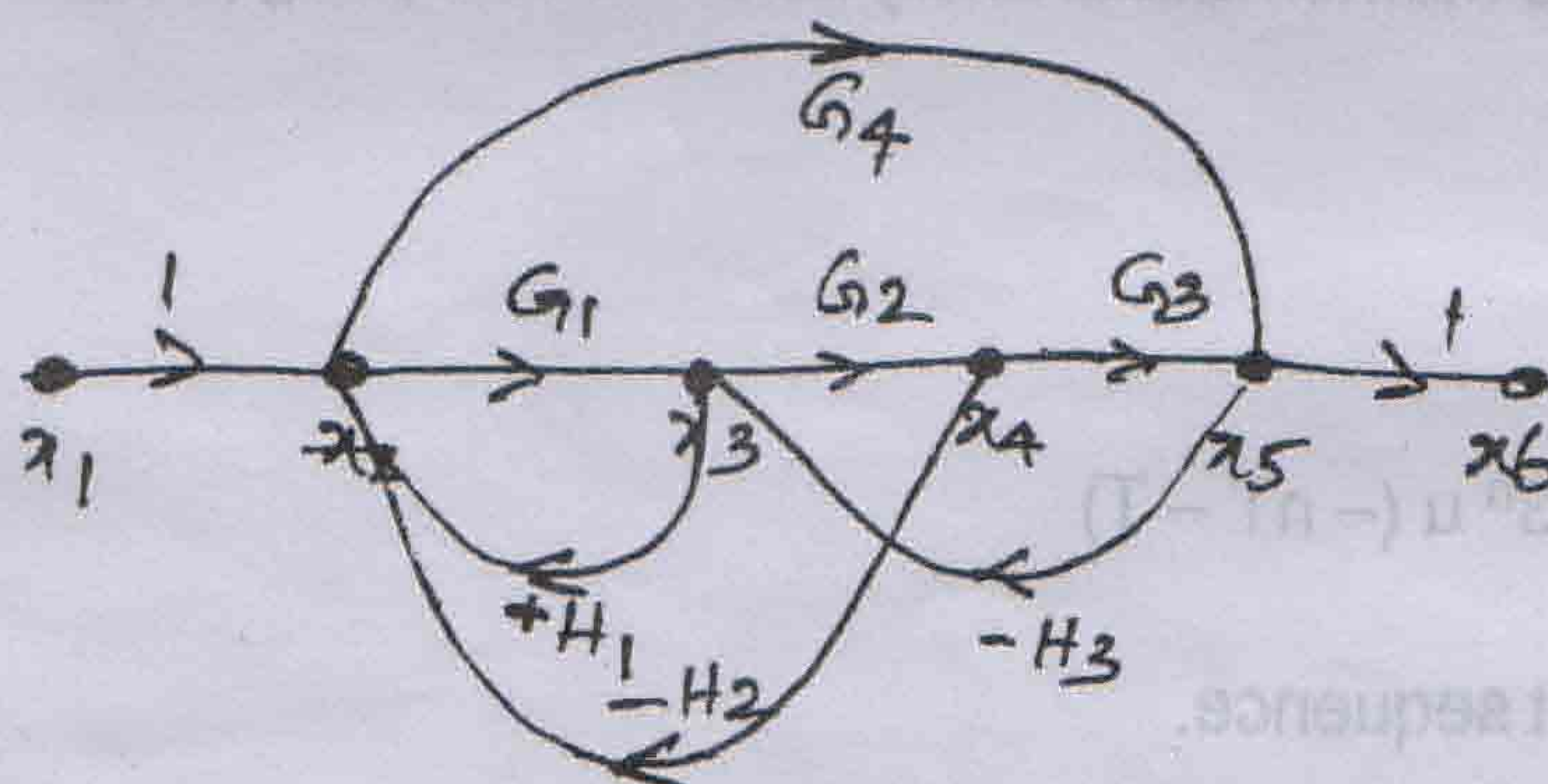
Time: 3 Hours

Max. Marks : 100

Instructions : Answer *all* questions.**Assume** the missing data suitably, *if any*.

1. a) What are the assumptions made for the derivation of Laplace transform ?
- b) State any two properties of a signal flow graph.
- c) Explain relative stability of a system.
- d) Explain how gain and phase margin are measured from Bode plot.
- e) Explain about sample data control systems.
- f) What is bilinear transformation ?
- g) Explain what is state and state variable representation.
- h) Compare the representation of a system in state space and transfer function. (8×5=40)

2. a) Find the transfer function x_5/x_1 for the system whose signal flow graph is given below : 15



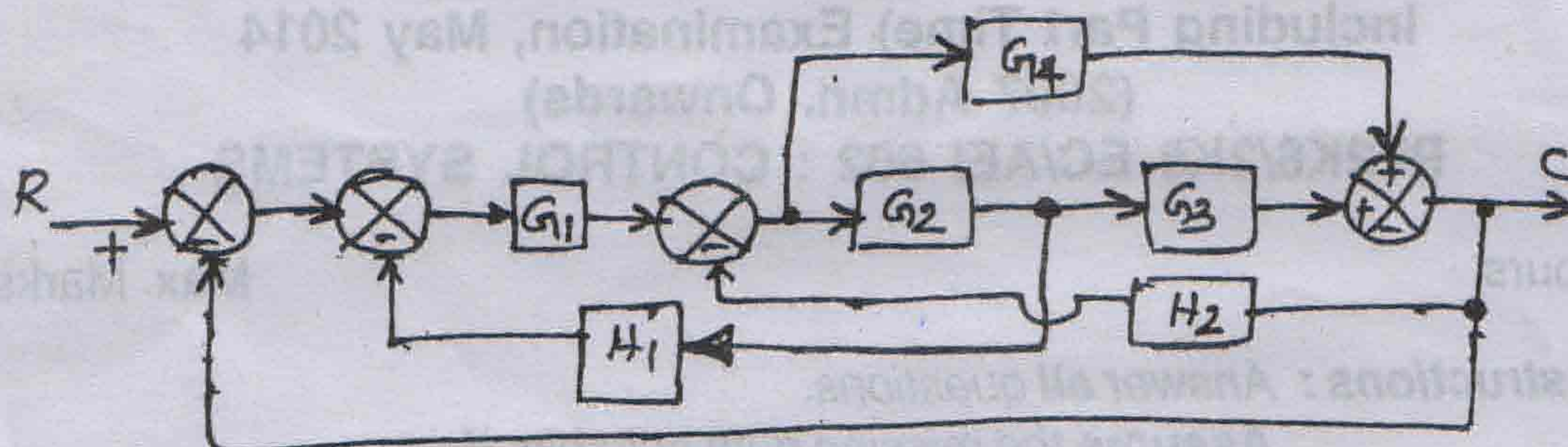
OR

P.T.O.



- b) Obtain the transfer function of the feedback control system by block diagram reduction technique.

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3. a) Sketch the root locus of the open loop transfer function :

$$G(s)H(s) = \frac{K}{s(s+2)(s^2+2s+5)}$$

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OR

- b) A unity feedback system has a plant transfer function of

$$G(s)H(s) = \frac{K(s+4)}{(s-1)(s-2)}$$

- 1) For $K = 8$, draw the Bode plots and find there from the PM and GM.
- 2) What should be the value of K for a phase margin of 30° and what is the corresponding gain margin ?

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4. a) Explain in detail about the mathematical analysis of the sampling process.

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OR

- b) Find the z-transform of

$$x(nT) = \left(\frac{1}{2}\right)^n u(nT) + 3^n u(-nT - T)$$

where $u(nT)$ denotes unit sequence.

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5. a) Obtain a state modes of the system described by the transfer function

$$\frac{y(s)}{u(s)} = \frac{5}{s^3 + 6s + 7}$$

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OR

- b) Obtain the response $y(t)$ of the following system.

$$\dot{X} = \begin{bmatrix} -1 & -0.5 \\ 1 & 0 \end{bmatrix} X + \begin{bmatrix} 0.25 \\ 0 \end{bmatrix} u$$

$$X(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ where } u(t) \text{ is the unit step input occurring at } t = 0.$$

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